Model 444 Alphaline[®] Temperature Transmitters





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Model 444 Alphaline[®] Temperature Transmitters

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Temperature Sensor Reference Information



Introduction

OVERVIEW

This manual is designed to assist in installing, operating, and maintaining $Rosemount^{$ Model 444 Alphaline Temperature Transmitters.

Section 2 Installation

provides mechanical, electrical, and environmental considerations to guide you through a safe and effective transmitter installation.

Section 3 Calibration

provides different Model 444 calibration procedures.

Section 4 Maintenance and Troubleshooting

provides hardware diagnostics, maintenance tasks, basic hardware troubleshooting techniques, and considerations for returning materials.

Section 5 Specifications and Reference Data

provides functional, performance, and physical transmitter specifications; also includes transmitter dimensional drawings, ordering information, and spare parts.

Section 6 Options

provides a listing of transmitter options and a description of each.

Appendix A Approval Drawings

contains approval drawings for Canadian Standards Association (CSA) and Factory Mutual (FM) instrinsic safety installation.

Appendix B Temperature Sensor Reference Information

provides reference information regarding the application of various Rosemount temperature sensors.



Installation

OVERVIEW

This section includes the following transmitter installation information:

- General Considerations
- Mechanical Considerations
 Mounting Stability
 Access Requirements
- Electrical Considerations
 - Power Supply Field Wiring Sensor Connections Grounding Multi-Channel Installations Surges/Transients
- Environmental Considerations
 - Temperature Environment Moist or Corrosive Environments Hazardous Location Installation Intrinsically Safe Installation
- Installation Procedure Mechanical Electrical

GENERAL CONSIDERATIONS

WARNING

Failure to follow these installation guidelines may result in death or serious injury. Make sure only qualified personnel perform the installation.

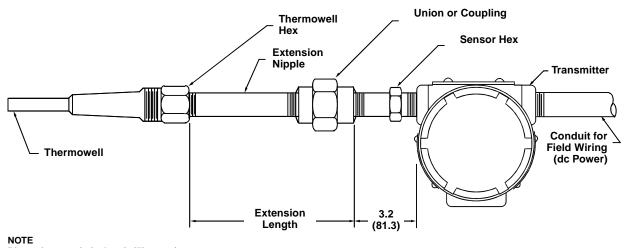
Explosions can cause death or serious injury. Verify that the operating atmosphere of the transmitter is consistent with the appropriate hazardous locations certifications.

Use the Rosemount Model 444 Alphaline Temperature Transmitter when the temperature measurement point is remote from the control, readout, or recording point, or where the measurement point is exposed to environmental conditions that would be harmful to unprotected signal conditioning equipment.

Electrical temperature sensors such as RTDs and thermocouples

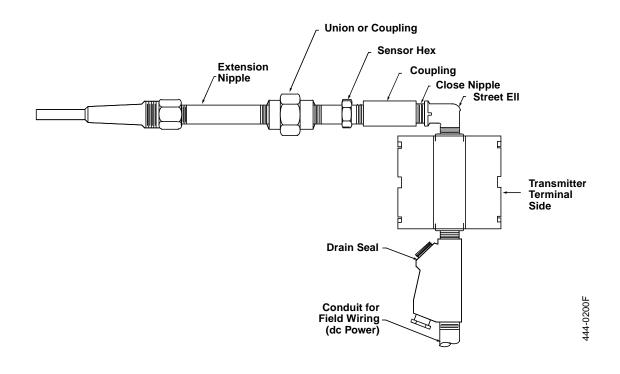
	produce low-level signals proportional to their sensed temperature. Model 444 temperature transmitters convert the low-level sensor signal to a standard 4–20 mA dc signal that is relatively insensitive to lead length and electrical noise. This current signal is then transmitted to the control room via two wires.
	Figures 2-1, and 2-2 show recommended mounting configurations for transmitter and sensor assemblies. See Section 6 Options for information regarding Model 444 transmitter accessories.
MECHANICAL CONSIDERATIONS	You can attach the transmitter directly to the sensor assembly as shown in Figures 2-1 and 2-2. An optional mounting bracket permits the transmitter to be mounted remotely from the sensor(s), either on a flat surface or attached to a two-inch pipe (See Figure 2-11 on page 2-13). The choice of mounting method must take into account a number of factors:
Mounting Stability	Mounting stability is an important consideration. The transmitter, though rugged, may require supplementary support under high-vibration conditions, particularly if extensive thermowell lagging or long extension fittings are used. In such instances, the pipestand mounting technique shown in Figure 2-11 on page 2-13 is preferable.
Access Requirements	When choosing an installation location and position, take into account the need for access to the transmitter.
Housing Rotation	You may rotate the transmitter in 90-degree increments to improve field access to both compartments.
Terminal Side of Electronics Housing	Make wiring connections through the conduit openings on the terminal side of the electronics housing. Mount the transmitter so the terminal side is accessible, and be sure to provide adequate clearance for cover removal.
Circuit Side of Electronics Housing	The transmitter electronics are installed in the circuit side of the transmitter housing. In case of electronic malfunction, provide adequate clearance for circuit-side cover removal. Also, be sure to account for additional clearance if a meter is to be installed. For more information regarding the meter option, refer to Section 6 Options .

FIGURE 2-1. Recommended Process Mounting.



Dimensions are in inches (millimeters).

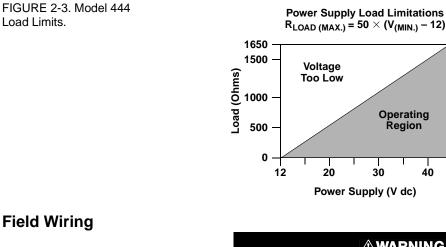
FIGURE 2-2. Recommended Process Mounting with Drain Seal.



ELECTRICAL CONSIDERATIONS

This section contains information that you should consider when preparing to install Model 444 transmitters. Read this section carefully before going on to the installation procedures. Metal conduit should be used to enclose cabling for best results in electrically noisy environments.

The dc power supply should provide power with less than 2% ripple. The input **Power Supply** voltage versus load limitation relationship for 4-20 mA transmitters is shown in Figure 2-3. Figure 2-4 shows field wiring for a standard Model 444 transmitter. Figure 2-5 shows field wiring for Models 444LL and 444LM low-power voltage output units, which require 100K ohms minimum load. The total R-load is the sum of the resistance of the signal leads and the load resistance of the controller, indicators, and related devices. Note that the resistance of intrinsic safety barriers, if used, must be included in the total load.



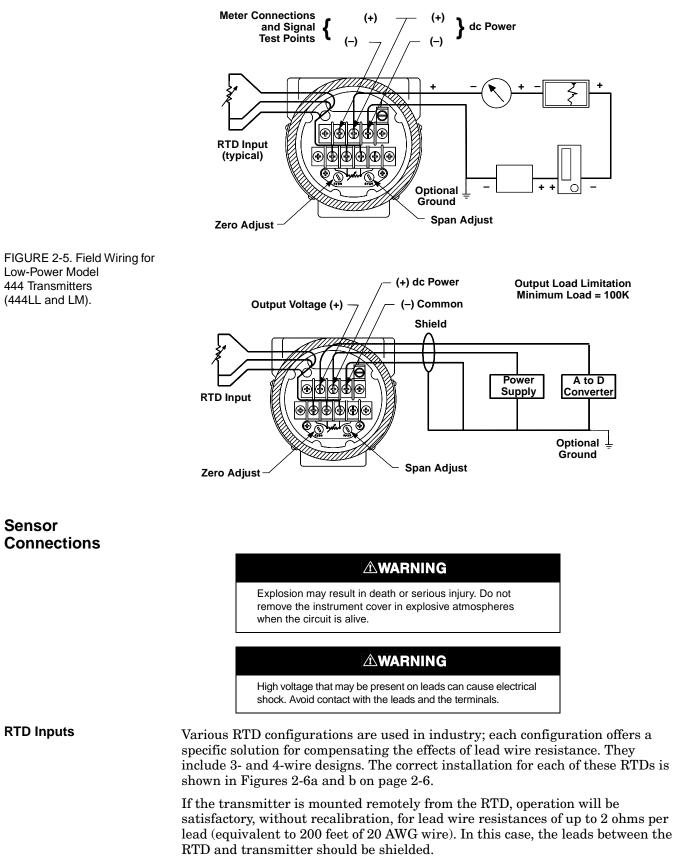
Explosions may result in death or serious injury. Do not remove the instrument cover in explosive atmospheres when the circuit is alive.

High voltage that may be present on leads can cause electrical shock. Avoid contact with leads and terminals.

Do not apply high voltage (e.g. ac line voltage) to the transmitter terminals. Abnormally high voltage can damage the unit.

All power to the transmitter is supplied over the signal wiring. Signal wiring need not be shielded, but use twisted pairs for best results. Do not run unshielded signal wiring in conduit or open travs with power wiring, or near heavy electrical equipment. To power the transmitter, connect the positive power lead to the terminal marked "+" and the negative power lead to the terminal marked "--" (see Figures 2-4 and 2-5). Tighten the terminal screws to ensure adequate contact. No additional power wiring is required.

FIGURE 2-4. Field Wiring for the Standard Model 444 Transmitters.



444-0000C02A

The correct connections for a compensation loop RTD and a 2-wire RTD are shown in Figure 2-6c and Figure 2-6d, respectively. In a 2-wire RTD, however, both leads are in series with the sensor element, so significant errors $(0.1 \ ^{\circ}C)$ could occur if the lead lengths are greater than one foot. For longer runs when using a 2-wire RTD, attach a third lead and connect as shown in Figure 2-6a.

FIGURE 2-6. Sensor Wiring Diagrams.

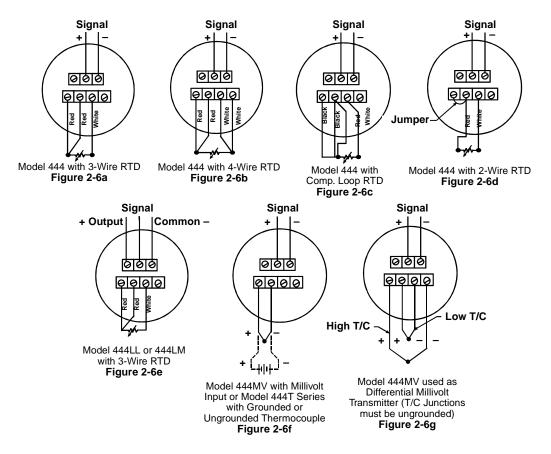
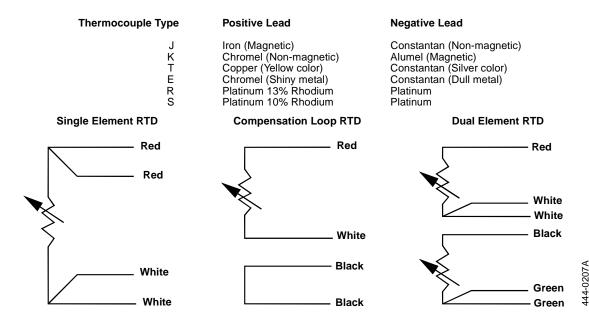
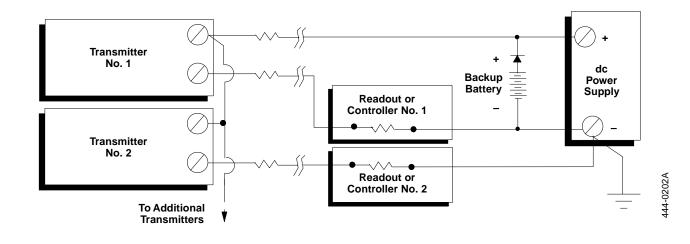


FIGURE 2-7. Characteristics of Thermocouple and RTD Input Wires.



Thermocouple or Millivolt Inputs	In the case of thermocouples, make connections between the sensor and the transmitter with thermocouple wire. For process mounting applications, connect the thermocouple directly to the transmitter. For installations where the transmitter is mounted remotely from the sensor, use appropriate thermocouple extension wire. As with all low-level signal wiring, shielding is recommended for long runs. Make input connections for the Model 444MV Millivolt Transmitter using copper wires. The correct connections for thermocouple and millivolt inputs are shown in Figures 2-6f and g.
Grounding	The transmitter will operate with the current signal loop either floating or grounded. However, many types of readout devices are affected by the extra noise in floating systems. If operation appears noisy or erratic, grounding the current signal loop at a single point may solve the problem. The negative terminal of the power supply is the best place to ground the loop. Alternately, either side of the readout device could be grounded. Do not ground the current signal loop at more than one point.
	Thermocouple and millivolt transmitters are isolated, so the input circuit also may be grounded at any single point (when a grounded thermocouple is used, this point is the grounded junction), and the signal loop may be grounded at any point.
	The 444RL transmitter is not isolated, so there can be no grounds in the RTD circuit. Since RTDs must be well-insulated from ground in order to give correct temperature readings, this is not normally an installation limitation. The positive side of the power supply should not be grounded for use with RTD input transmitters. The 444RI9 should be used with grounded RTDs.
	If using shielded wire, connect the shield of the sensor-to-transmitter cable to the shield of the transmitters-to-receiver cable. Ground the shielding only at the signal loop ground.
Multi-Channel Installations	Figure 2-8 illustrates how several transmitters can be connected to a single master power supply. In this instance, the system can be grounded only at the negative power supply terminal. Since several channels are dependent on one supply, an uninterruptible power supply or backup battery should be considered if loss of all channels would pose operational problems. The diodes shown in Figure 2-8 prevent unwanted charging or discharging of the battery.

FIGURE 2-8. Multi-Channel Installation.



Surges/Transients The transmitter will withstand electrical transients of the energy level usually encountered in static discharges or induced switching transients. However, high-energy transients, such as those induced in wiring from nearby lightning strikes, can damage both the transmitter and the sensor.

To protect against high-energy transients, install Model 444 transmitters in conjunction with the Rosemount Model 470 Transient Protector. The Model 470 prevents damage from transients induced by lightning, welding, heavy electrical equipment, or switch gears. Refer to the Model 470 Transient Protector product data sheet, pub. no. 00813-0100-4191 for more information.

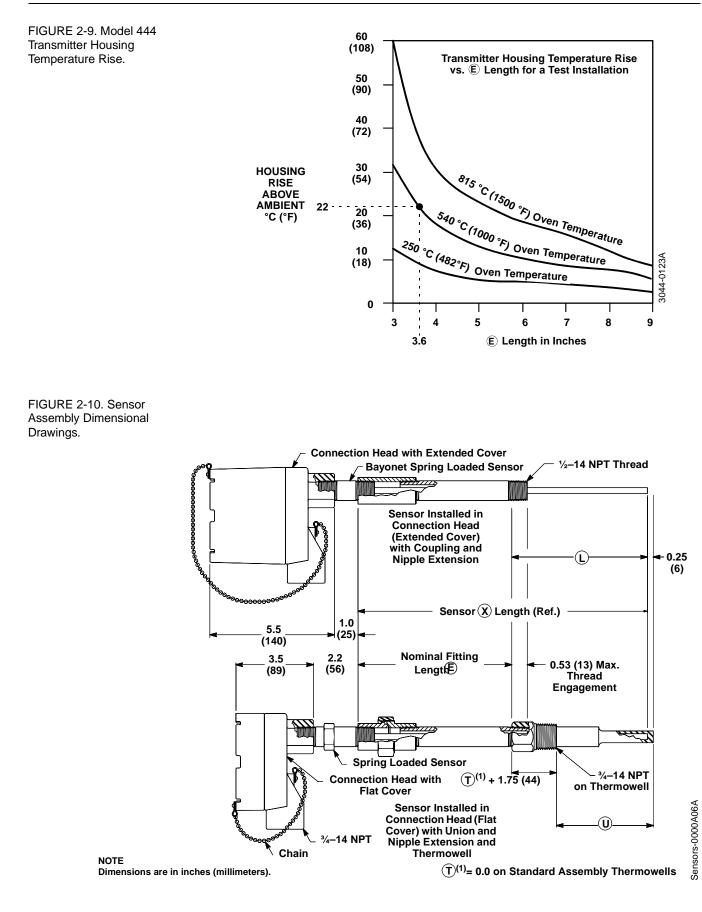
ENVIRONMENTAL CONSIDERATIONS

Temperature Environment The transmitter will operate within specifications for ambient temperatures between -25 and 85 °C. It will function, but not necessarily within specifications, in ambient temperatures between -40 and 100 °C.

Aside from ambient temperature variations, heat from the process is transferred from the thermowell to the transmitter housing. If the process temperature is near or beyond specification limits, use excess thermowell lagging or an extension nipple to protect the transmitter from the high temperature condition. See Figure 2-10.

EXAMPLE:

Suppose the maximum ambient temperature is 40 °C and the temperature to be measured is 540 °C. The maximum allowable housing temperature rise is the rated temperature specification limit minus the existing ambient temperature (85 - 40), or 45 °C. As shown in Figure 2-9, an "E" dimension of 3.6 inches will result in a housing temperature rise of 22 °C. An "E" dimension of 4 inches would therefore be the minimum recommended length, and would provide a safety factor of about about 25 °C. A longer "E" dimension, such as 6 inches, would be desirable in order to reduce errors caused by transmitter temperature effect, although in that case the transmitter would probably require extra support. If a thermowell with lagging is used, the "E" dimension may be reduced by the length of the lagging.



Moist or Corrosive Environments

The transmitter is designed to resist attack by moisture and other corrosives. The coated circuit boards are mounted in a compartment completely sealed from the conduit entrances. O-ring seals protect the interior when the covers are installed. In humid environments, however, it is still possible for moisture "breathing" to occur in conduit lines. If the transmitter is mounted at a low point in the conduit run, the terminal compartment could fill with water, causing electrical shorting. The transmitter should be mounted so moisture from the conduit will not drain into the housing. In some instances a drain seal, installed as shown in Figure 2-2 on page 2-3, is advisable.

Hazardous Location Installation

AWARNING

Explosions may result in death or serious injury. Verify that the operating atmosphere of the transmitter is consistent with the appropriate hazardous locations certifications.

AWARNING

Explosions may result in death or serious injury. Both transmitter covers must be fully engaged to meet explosion-proof requirements.

The Model 444 is designed with an explosion-proof housing and circuitry suitable for intrinsically safe and non-incendive operation. Individual transmitters are clearly marked with a tag indicating the approvals they carry. The various approvals are available as options. Refer to **Section 5 Specifications and Reference Data** for a complete listing of available approvals.

To maintain certified ratings for installed transmitters, install in accordance with applicable installation codes and approval drawings. Refer to **Appendix A Approval Drawings** for Model 444 installation drawings. For future orders, refer to the current product price list for the most up-to-date information on these approvals.

Intrinsically Safe Installation

For explosion-proof installations, installation location must be made in accordance with Rosemount drawing 00444-0261, Rev. E.

For intrinsically safe installations, installation location must be made in accordance with Rosemount drawing 00444-0034, Rev. C (CSA) or 00444-0264, Rev. B (SAA).

You can use Intrinsically safe installations instead of explosion-proof installations in hazardous areas. In such configurations, the transmitter and sensor are located in a hazardous area, and the current signal leads are connected to equipment in a non-hazardous area through intrinsic safety barriers that limit the voltage and current fed into the hazardous area. Install in accordance with the barrier manufacturer's instructions for the specific barrier used. For approval information, refer to Table 5-1 on page 5-4, and Table 5-2 on page 5-5. For installation information, refer to the intrinsically safe barrier systems reference drawings in **Appendix A Approval Drawings**.

INSTALLATION PROCEDURE

Installation consists of mounting the transmitter and sensor assembly and making electrical connections. If mounting the transmitter directly to the sensor assembly, use the process mounting technique shown in Figure 2-1 or Figure 2-2, on page 2-3. For transmitter locations remote from the sensor, use conduit between the sensor and transmitter. Transmitter hubs will accept male conduit fittings with $\frac{1}{2}$ -14 NPT; $\frac{1}{2}$ -14 NPSM; or $\frac{1}{2}$ -14 taper thread per ANSIC 80.4.

Explosion may result in death or serious injury. Do not remove the instrument cover in explosive atmospheres when the circuit is alive.

AWARNING

High voltage that may be present on leads may cause electrical shock. Avoid contact with the leads and the terminals.

AWARNING

Process leaks may result in death or serious injury. Install and tighten thermowells or sensors before applying pressure, or process leakage may result. Removing the thermowell or sensor while in operation may cause process fluid leaks.

Mechanical

- 1. Mount the thermowell to the pipe or process container wall.
- 2. Attach any necessary extension nipples and adapters. Seal the nipple and adapter threads with silicone or tape.
- 3. Screw the sensor into the thermowell.
- 4. Install drain seals if required for severe environments or to satisfy code requirements (See Figure 2-2 on page 2-3).
- 5. Attach the transmitter to the thermowell assembly. Seal the adapter threads with silicone or tape.
- 6. Install conduit for field wiring to the remaining conduit entry of the transmitter. Seal conduit threads with silicone or tape.
- 7. Pull field wiring leads through the conduit into the terminal side of the transmitter housing.

Electrical

AWARNING

For explosion-proof installations, wiring connections must be made in accordance with Rosemount drawing 00444-0261, Rev. E. For intrinsically safe installations, wiring connections must be made in accordance with ANSI/ISA-RP12.6, and Rosemount drawing 00444-0034, Rev. C (CSA) or 00444-0264, Rev. B (SAA).

For all installations, wiring connections must follow the National Electric Code.

Preliminary Checkout

1. For any Model 444 unit, first verify that the transmitter is calibrated to the required range. Calibration is usually performed by substituting an input in place of the sensor, and this is most conveniently accomplished prior to sensor connection. Refer to the calibration procedures in **Section 4 Maintenance and Troubleshooting**.

Input Connections

2. **Model 444RL:** Connect the RTD leads as shown in Figure 2-6a, b, c, d, or e depending upon the lead compensation method used.

Model 444T series: Connect the thermocouple leads as shown in Figure 2-6f. Polarity is important; be sure to identify the leads accurately. The negative lead is usually red; if there is no color coding, the characteristics provided in Figure 2-7 may be helpful.

Model 444MV: If using the transmitter as a millivolt-to-milliampere converter, use ordinary copper leads for input connections as shown in Figure 2-6f. If using the transmitter with two thermocouples to measure differential millivolt, connect the thermocouples as shown in Figure 2-6g. The "high" thermocouple causes the transmitter output to increase when its temperature increases relative to the "low" thermocouple. Grounded thermocouples cannot be used for differential measurements.

Models 444LL and LM: In these low-power option packages, the RTD leads are connected the same as in the conventional RTD arrangements shown in Figure 2-6a, b, c, and d.

Output Connections

3. For all 4–20 mA models, use ordinary copper wire of sufficient size to assure that the voltage across the transmitter power terminals does not go below 12 V dc (See Figure 2-3). For multi-channel or intrinsically safe installations, see applicable paragraphs in this section.

Model 444RL: Connect current signal leads as shown in Figure 2-6a, b, c, or d.

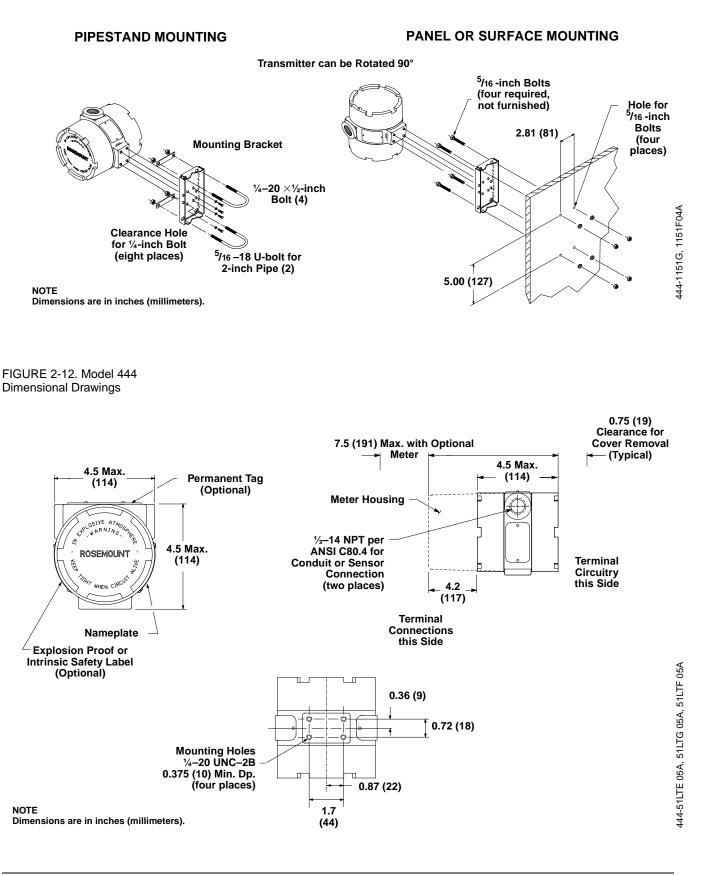
Model 444T series: Connect current signal leads as shown in Figure 2-6f.

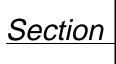
Model 444MV: Connect current signal leads as shown in Figure 2-6f or g. **Models 444LL and LM:** Connect current signal leads as shown in Figure 2-6e.

Final Checkout

4. For all models, recheck the polarity and correctness of connections; then turn the power on.

FIGURE 2-11. Model 444 with Optional Mounting Bracket.





Calibration

OVERVIEW

Each transmitter is factory calibrated to the temperature range shown on the nameplate. If calibration to a specific range is not specified on the purchase order, the transmitter is calibrated to maximum span with a base temperature of 0 °C, and the "Calibration" entry on the transmitter nameplate is left blank. For more specific calibration information and a complete breakdown of transmitter parts, refer to **Section 5 Specifications and Reference Data**.

Only a few calibration laboratories have the kind of precision temperature baths necessary for accurate direct calibration of a temperature sensor or sensor/transmitter system. As a result, the transmitter is normally calibrated by substituting a resistance decade box for an RTD or a compensated thermocouple simulator for a thermocouple.

This section contains the following transmitter calibration information:

- Calibrating a RTD Transmitter
- Calibrating a Thermocouple Transmitter
- Calibrating a Low-Power Transmitter
- Calibrating a Millivolt Transmitter

SAFETY MESSAGES

This section contains procedures that require removing the transmitter covers and making electrical connections. The following safety messages apply to all such procedures.

AWARNING

Explosion may result in death or serious injury. Do not remove the instrument cover in explosive atmospheres when the circuit is alive.

AWARNING

High voltage that may be present on leads can cause electrical shock. Avoid contact with the leads and the terminals.

CALIBRATING A RTD TRANSMITTER	 Calibration Equipment Required: Readout Resistor. The transmitter test terminals give a 40–200 mV signal. The Models 444RL and444RLB0912 have a jumper-selectable 4–20 mA test output option (2-board sets). If this is not suitable for the test equipment available, a ±0.1% tolerance, 0.5 W precision wirewound resistor is needed. Suggested values include a 100-ohm resistor to give a 0.4 to 2 volt output; or 500 ohms for 2 to 10 volts. Voltmeter (such as a 5-digit DVM). Voltage rating is dependent upon the test signal. Accuracy is ±0.01%; resolution is 1 mV. dc Power Supply. Power capability is 24 V dc at 35 mA. Resistance Decade Box. Precision type, 5-dial, with largest dial providing 100-ohm steps. Accuracy is ±0.02 ohm. The decade box should be periodically calibrated against a 5-dial Wheatstone bridge. Lead Simulation Resistors. If the transmitter is to be mounted remote from the
	RTD, and the lead resistance between the transmitter is to be inculted related related resistance from the RTD, and the lead resistance between the transmitter and the RTD is greater than 2 ohms per lead (equivalent to 200 ft of 20 AWG wire), the transmitter should be trimmed with simulated lead resistances for best accuracy. This requires wirewound resistors with resistance values equal to the nominal lead resistance of the RTD.
Calibration Procedure	 To calibrate a model 444RL or 444RLB0912, perform the following procedure: 1. The Models 444RL and 444RLB0912 have a jumper-selectable 4–20 mA test output option. If a 4–20 mA test output is required, reposition the test terminal output jumper on the range board (the default setting is 40–200 mV). Refer to steps 2 through 4 of the disassembly procedure, on page 4-4, for information on removing the circuit board assembly. Place the jumper in the position labelled "A" for a 4–20 mA test output. See Figure 3-1. Refer to steps 5 through 12 of the reassembly procedure, on page 4-5, for information on reinstalling the circuit board assembly. 2. Remove the cover from the terminal side of the transmitter housing. 3. If an RTD is already connected, remove all RTD lead connections. 4. Attach the calibration test equipment as shown in Figure 3-2. Use miniature banana plugs to make terminal connections. Use simulated lead
	 NOTE If using RTD configurations other than the 3-wire design shown in Figure 3-2, refer to Figure 2-6 on page 2-6 for the correct wiring. 5. If trimming the transmitter to a new range, you may have to reposition the Coarse Zero Jumper on the Range Board. If so, see the disassembly procedure on page 4-4. Position the jumper in the location shown in Table 3-1. (A transmitter with a Base Temperature outside the regions shown in Table 3-1 is a special design, and does not contain a Coarse Zero Jumper.) Reassemble the circuit boards.

- 6. Determine the RTD resistance at the desired base and full scale temperatures. For Calibration Code 1 (see Table 5-3, on page 5-9), these resistances are listed in Table B-1.
- 7. Turn the power on.
- 8. Set the decade box to the resistance corresponding to the desired base temperature. Adjust the zero potentiometer until the output is 4 mA. Remember that recovery time of the unit from an underscale condition is longer than from an over-scale condition. Therefore, set the box to a higher resistance than that desired, then bring it down to the correct value.
- 9. Set the decade box to the resistance corresponding to the desired full scale temperature. Adjust the span potentiometer until the output is 20 mA.
- 10. Repeat steps 8 and 9 until you obtain the 4 and 20 mA readings without readjusting the span and zero potentiometers. Complete this process more quickly by noting the full scale reading before readjusting the span pot, using the span pot to overshoot the desired reading by 20%, and then using the zero pot to readjust the full scale reading to 20 mA.

EXAMPLE:

To calibrate the Model 444RL1U1 for a range of 100 to 150 °F (38 to 66 °C), first consult Table 3-1, and plug the jumper into pins Z2. From Table B-1, trim points are 114.68 and 125.37 ohms corresponding to 100 °F and 150 °F respectively. After adjusting the base to 4 mA, and setting the decade to full scale resistance, output equals 22.5 mA, or 2.5 mA greater than desired. Set the span pot to an output lower than 20 mA by the amount equal to 20% of 2.5 equals 0.5 mA, or 19.5 mA. Reset the zero pot so the output equals 20 mA. Repeat steps 8 and 9 and this procedure until readjustments are no longer necessary.

- 11. Disconnect the decade box and the readout resistor. Reconnect the RTD and power leads. Replace the terminal cover.
- 12. Mark the correct range in the "Calibration" space on the nameplate

Base Temperature Region		Jumper Location		
°C °F		444RL1	444RL2	444RL3
-50 to 0 0 to 50 50 to 100 100 to 150	-58 to 32 32 to 122 122 to 212 212 to 302	Z1 Z2 Z3 Z4	Z1 Z1 Z2 Z2	Continuously adjustable (no jumper)
NOTE If the base temperature is at a dividing point between regions, use the lower jumper position optimum performance; i.e., use location Z1 rather than Z2 for Model 444RL1 with a base temperature of 0 °C.				

TABLE 3-1. Coarse Jumper Location, Model 444R.

FIGURE 3-1. Location of Test Input and Burnout Protection Jumper on Model 444RL Range Board.

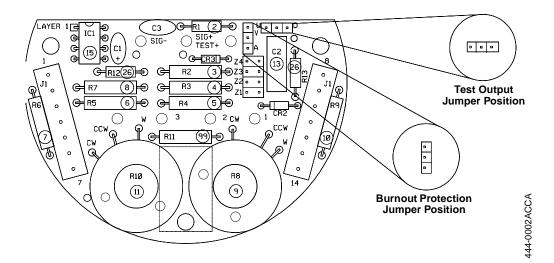
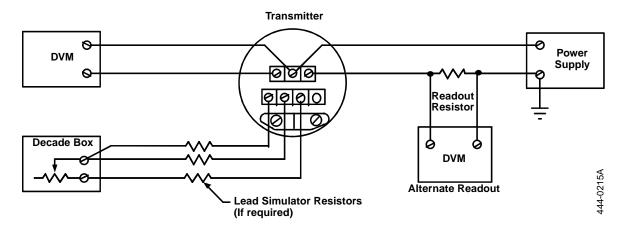


FIGURE 3-2. RTD Transmitter Calibration Diagram.



CALIBRATING A THERMOCOUPLE TRANSMITTER

Using a Compensated Thermocouple Simulator	Calibration Equipment Required Compensated Thermocouple Simulator. Precision voltage source providing conformity to NIST Monograph 125 thermocouple curves. Reflect accuracy of simulator to desired calibration span. A simulator accuracy four times better than the transmitter is recommended (0.05% of calibrated span or 0.005 mV whichever is greater). Simulator inaccuracies greater than this will degrade system accuracy and factory calibration is recommended. <i>Voltmeter</i> . Such as a 5-digit DVM. Accuracy is $\pm 0.01\%$; resolution is 1 mV. <i>dc Power Supply</i> . Power capability is 24 Vdc at 35 mA. <i>Thermocouple Wire</i> . Use the same type as that used in the construction of the thermocouple. <i>Readout Resistor</i> . The transmitter test terminals give a 40–200 mV signal. If this is not suitable for the test equipment available, a $\pm 0.1\%$ tolerance, 0.5 W precision wirewound resistor is needed. Suggested values include a 100-ohm resistor to give a 0.4 to 2 volt output; 250 ohms for 1 to 5 volts; or 500 ohms for 2 to 10 volts.
Calibration Procedure	1. Remove the cover from the terminal side of the transmitter housing.
	2. If a thermocouple is already connected, remove all thermocouple lead connections.
	 Connect the equipment as shown in Figure 3-4. Be sure to maintain polarity from the transmitter to the thermocouple simulator. Make terminal connections using miniature banana plugs.
	4. If trimming the transmitter to a new range, you may have to reposition the Coarse Zero Jumper on the Range Board. If so, see the Disassembly Procedure on page 4-4. Position the jumper in the location shown in Table . (A transmitter with a base temperature outside the regions shown in Table is a special design and does not contain a Coarse Zero Jumper. Also, Model 444 TR and TS transmitters do not have Coarse Zero Jumpers.) Reassemble the circuit boards.
	5. Determine the base and full scale temperatures.
	6. Turn the power on.
	7. Refer to the thermocouple simulator instructions for setting the thermocouple type and engineering units. Set the simulator to the base (zero) temperature and adjust the zero pot until the output is 4 mA (or 40 mV at the test terminals).
	8. Set the simulator to the full scale temperature and adjust the span pot until the output is 20 mA (or 200 mV at the test terminals).
	9. Repeat steps 7 and 8 until you obtain the 4 and 20 mA readings without readjusting the pots. Use the "overshoot" technique described in step 9 of the RTD calibration procedure, if desired.
	10. Disconnect the simulator leads. Reconnect the thermocouple and power leads, if required. Replace the terminal side housing cover.
	11. Mark the new range in the "Calibration" space on the nameplate.

TABLE 3-2. Coarse Zero Jumper Location, Model 444TJ, TK, TF, TT, and MV Range Code 1.

Tran	Coarse Zero			
°C	°F	mV	Jumper Location	
-50 to 50	-58 to 122	-2 to 3	Z1	
50 to 100	122 to 302	3 to 8	Z2	
NOTE Range Codes 2 and 3 are continuously adjustable over the range				

shown in Table 1. (No Coarse Zero Jumper)

FIGURE 3-3. Location of Burnout Protection Jumper on Model 444T Range Board.

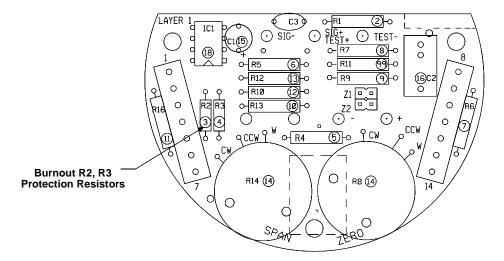
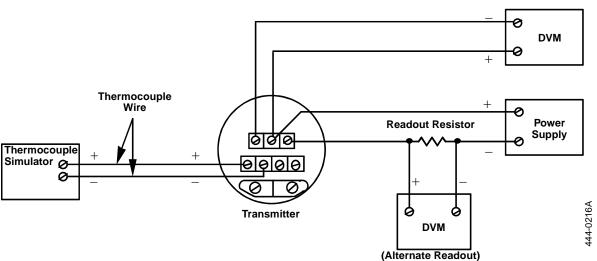
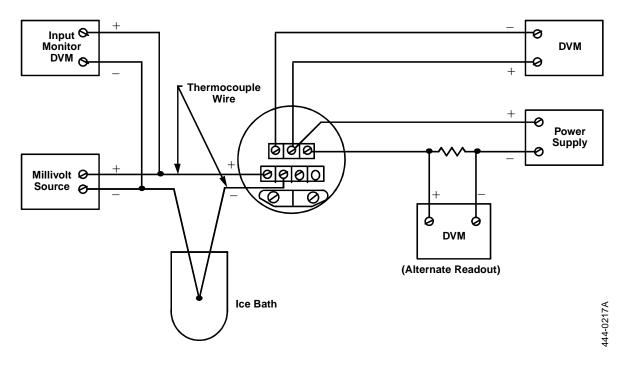


FIGURE 3-4. Compensated Thermocouple Simulator Calibration Diagram.



Using an Ice Bath	Calibration Equipment Required <i>Millivolt Source.</i> Precision voltage source providing outputs from -10 to 100 mV. Reflect accuracy of four times better that the 444 transmitter is recommended (0.05% of calibrated span or 0.005 mV which ever is greater).
	<i>Voltmeter.</i> Such as a 5-digit DVM. Accuracy is $\pm 0.01\%$; resolution is 1 mV.
	dc Power Supply. Power capability is 24 V dc at 35 mA.
	<i>Thermocouple Wire</i> . Use the same type as that used in the construction of the thermocouple.
	<i>Readout Resistor.</i> The transmitter test terminals give a 40–200 mV signal. If this is not suitable for the test equipment available, a $\pm 0.1\%$ tolerance, 0.5 W precision wirewound resistor is needed. Suggested values include a 100-ohm resistor to give a 0.4 to 2 volt output; 250 ohms for 1 to 5 volts; or 500 ohms for 2 to 10 volts.
	<i>Ice Bath.</i> For highest accuracy, a stirred ice bath (such as a Rosemount 911A) should be used, as well as ice made from deionized or distilled water.
	Input Monitor Voltmeter. Use to monitor source when required. Resolution of ± 0.001 mV for ranges up to 100 mV. This can be the same as voltmeter used to measure transmitter output if rangeability and resolution are sufficient for both levels.
Calibration Procedure	1. Remove the cover from the terminal side of the transmitter housing.
	2. Install the equipment as shown in Figure 3-5 and allow the thermocouple junctions to stabilize at the ice point. Make terminal connections with miniature banana plugs.
	3. If trimming the transmitter to a new range, you may have to reposition the Coarse Zero Jumper on the Range Board. If so, see the disassembly procedure on page 4-4. Position the jumper in the location shown in Table . (A transmitter with a base temperature outside the regions shown in Table is a special design and does not contain a Coarse Zero Jumper. Also, Model 444 TR and TS transmitters do not have Coarse Zero Jumpers.)
	4. Determine the thermocouple millivolt levels at the desired base and full scale temperatures. See NIST Monograph 125 or Table B-1.
	5. Turn the power on.
	6. Set the millivolt source until the monitoring voltmeter reads the emf corresponding to the desired base temperature. Adjust the zero pot until the output is 4 mA.
	7. Set the millivolt source until the monitoring voltmeter reads the emf corresponding to the desired full scale temperature. Adjust the span pot until the output is 20 mA.
	8. Repeat steps 6 and 7 until you obtain the 4 and 20 mA readings without readjusting the pots. Use the "overshoot" technique described in step 9 of the RTD calibration procedure, if desired.
	9. Mark the correct range in the "calibration" space on the nameplate.

FIGURE 3-5. Ice Bath Calibration Diagram.



CALIBRATING A LOW-POWER TRANSMITTER

Calibration Equipment Required

Voltmeter. Such as a 5-digit DVM. Accuracy is $\pm 0.01\%$; resolution is 1 mV. *dc Power Supply.* Power capability is 5 V dc at 1.5 mA for Model 444LL and 8 V dc at 2 mA for Model 444LM.

Resistance Decade Box. Precision type, 5-dial, with largest dial providing 100ohm steps. Accuracy is ± 0.02 ohm. The decade box should be periodically calibrated against a 5-dial Wheatstone bridge.

Lead Simulation Resistors. If the transmitter is to be mounted remote from the RTD, and the lead resistance between the transmitter and the RTD is greater than 2 ohms per lead (equivalent to 200 ft of 20 AWG wire), the transmitter should be trimmed with simulated lead resistances for best accuracy. This requires wirewound resistors with resistance values equal to the nominal lead resistance of the RTD.

Load Resistor. If the transmitter is to be operated with a load that is significantly different from the DVM used for calibration, a load resistor can be used for best calibration accuracy. A metal film, carbon comp, or wirewound resistor, as well as a decade box can be used to simulate the actual load.

Calibration Procedure

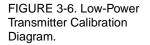
The following steps describe the procedure for calibrating a low-power transmitter, as shown in Figure 3-6:

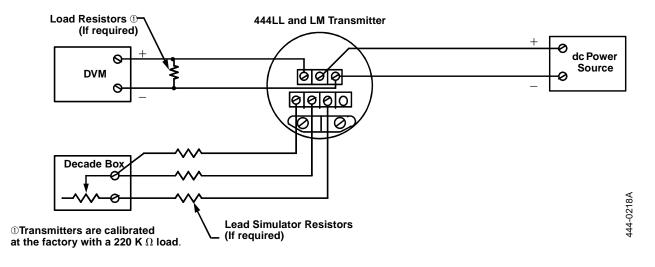
- 1. Remove the cover from the terminal side of the transmitter housing.
- 2. If an RTD is already connected, remove all RTD lead connections.
- 3. Attach the calibration test equipment as shown in Figure 3-6. Make terminal connections using miniature banana plugs. Use simulated lead resistors only if necessitated by long lead wire lengths, as discussed above.

NOTE

If using RTD configurations other than the 3-wire design shown in Figure 3-2, refer to Figure 2-6 on page 2-6 for the correct wiring.

- 4. Determine the RTD resistance at the desired base- and full-scale temperatures. For Calibration Code 1 (see Table 5-5), obtain these resistances from Table B-1.
- 5. Turn the power on.
- 6. Set the decade box to the resistance corresponding to the desired base temperature. Adjust the zero potentiometer until the output is 0.8 V for Model 444LL or 1.0 V for Model 444LM.
- 7. Set the decade box to the resistance corresponding to the desired full-scale temperature. Adjust the span potentiometer until the output is 3.2 V for Model 444LL or 5.0 V for Model 444LM.
- 8. Repeat steps 6 and 7 until you obtain both the zero- and full-scale readings without adjusting the span and zero potentiometers. Complete this process more quickly by noting the full-scale reading before readjusting the span pot, using the span pot to overshoot the desired reading by 20%, and then using the zero pot to readjust the full scale reading.
- 9. Disconnect the decade box and the readout. Reconnect the RTD and power leads. Replace the terminal cover.
- 10. Mark the correct range in the "Calibration" space on the nameplate.





CALIBRATING A MILLIVOLT TRANSMITTER

Calibration is identical to the thermocouple type (see Figure 3-5 on page 3-8), except that a reference junction and ice bath are not used. The millivolt source is connected directly to the transmitter input terminals with copper wire, and the desired millivolt levels are entered directly. See Table 3-2 for Coarse Zero Jumper locations.



OVERVIEW

Troubleshooting

This section contains the following transmitter maintenance and troubleshooting information:

Hardware Diagnostics

- Troubleshooting
- Repair
 - Disassembly Procedure Reassembly Procedure Interchangeability of Parts Burnout Protection Adjustments
- Repair and Warranty Service

Maintenance and

• Return of Materials

WARNING

Use only the procedures and new parts specifically referenced in this manual. Unauthorized procedures or parts can affect product performance and the output signal used to control a process, and may render the instrument dangerous. Direct any questions concerning these procedures or parts to Rosemount Inc.

If you suspect a malfunction, refer to Table 4-1 to verify that transmitter hardware and process connections are in good working order. Under each of the seven major symptoms, you will find specific suggestions for solving the problem. Always deal with the most likely and easiest-to-check conditions first.

TROUBLESHOOTING

HARDWARE

DIAGNOSTICS

This section offers tips for troubleshooting several kinds of potential malfunctions. To determine a malfunction, use pin-like probes to break through the protective coating to make measurements on a circuit board.

TABLE 4-1. Transmitter Troubleshooting Symptoms and Corrective Actions.

Symptom	Potential Source	Corrective Action		
High Output	Sensor	Check for a sensor or thermocouple open circuit. (RL, MV, T-Series with upscale burnout protection only)		
	Loop Wiring	Check for dirty or defective terminals, interconnecting pins, or receptacles.		
	Electronics Assembly	Check for dirty or defective interconnecting pins.		
Erratic Output	Loop Wiring	Check for adequate voltage to the transmitter. Check for intermittent shorts, open circuits, and multiple grounds. Check for dirty or defective terminals or interconnection pins.		
	Electronics Assembly	Check for dirty or defective interconnecting pins.		
Low Output or No Output	Sensor	Check RTD leads to ensure that they are not shorting together or to ground. (RL only) Check for correct RTD lead connection. (RL only) Check for open RTD lead on double-lead side. (RL only)		
	Loop Wiring	Check for adequate voltage to the transmitter. (RL only) Check for intermittent shorts, open circuits, and multiple grounds. (MV, T series only) Check for proper polarity at the signal terminal. (MV, T series only) Check for dirty or defective terminals or interconnection pins.		
Excessive Current (over 30 mA)	Loop Wiring	Check for short between current signal leads. Check to ensure that current signal leads ARE NOT connected to sensor terminals. Check that sensor leads ARE NOT grounded when positive side of power supply is grounded (RL, RLB0912, LL, and LM)		
	Electronics Assembly	Check for defective components in amplifier or current control section.		
Excessive	Sensor	Check for incorrect thermocouple type or Incorrect thermocouple polarity connection (T series only)		
Output Shift with Ambient Temperature	Electronics Assembly	Check to ensure that the burnout -protection jumpers positioned correctly (MV, T series only). Check for defective components in voltage regulator or dc-to-ac converter section (MV, T series only). Check for defective components in amplifier or current control section (all models). May require replacement electronics assembly.		
Unit Cannot be	Transmitter	Check to ensure that unit is capable of desired range.		
Trimmed to Desired Base Temperature	Electronics Assembly	Check to ensure that the range board jumper is in the correct position. Check to ensure that the burnout -protection jumpers positioned correctly. (MV, T series only). Check for defective zero pot.		
Unit Cannot be	Transmitter	Check to ensure that unit is capable of desired range.		
Trimmed to Desired Span.	Loop Wiring	Check for adequate voltage to the transmitter.		
	Electronics Assembly	Check for defective components in amplifier or current control section. Check for defective components in voltage regulator section. Check for defective span pot.		

REPAIR

AWARNING

Exposure to hazardous substances can cause death or serious injury. If a hazardous substance is identified, a Material Safety Data Sheet (MSDS), required by law to be available to people exposed to specific hazardous substances, must be included with the returned materials.

In case of a failure, particularly one in which the transmitter's output goes to one extreme and stays there, the first step is to determine whether the fault lies with the sensor(s) or the transmitter. Although only a careful calibration can determine sensor shifts, catastrophic failures (such as an open or shorted sensor element) can be checked with an ohmmeter at the time the transmitter is disconnected from the sensor(s).

NOTE

The Resistance vs. Temperature and Millivolt vs. Temperature tables for the standard Model 444 sensor input types are presented in Table B-1 in **Appendix B Temperature Sensor Reference Information.**

RTD Test: A platinum RTD with an ice-point (°C) resistance of 100 ohms should read approximately as shown in Table B-1 at other temperatures. The resistance between the two leads on the same side of the sensing element should be low, a few ohms at most. Resistance between any of the RTD leads and the sensor sheath should be high

(1 megohm or greater).

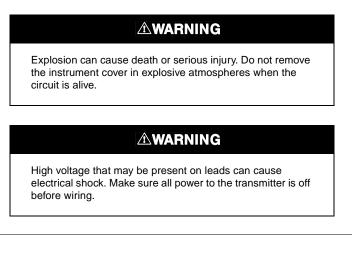
Thermocouple Test: Thermocouple resistance should be low (10 ohms or less for short runs of heavy wire). For longer runs of extension wire, resistance will be roughly ten times the resistance of copper wire of the same diameter. If the sensor and receiving equipment are functioning properly, the transmitter will probably require repair.

The transmitter is designed for easy replacement of its plug-in, modular circuit boards. A malfunction can be most easily isolated by substituting boards one at a time until the unit functions properly.

It is recommended that customers return defective circuit boards to Rosemount Inc. for repair (see "RETURN OF MATERIALS" on page 4-6). This ensures that replacement parts meet the design criteria for the board and that the malfunctioning board is completely checked and repaired.

Rosemount Inc. offers a circuit board repair/replacement program through its many service centers. Please contact your Rosemount field sales office for price and delivery information.

Disassembly Procedure



NOTE

The numbers in parentheses refer to parts shown in the Illustrated Parts List, Table 5-7, in **Section 5 Specifications and Reference Data**.

- 1. Terminal blocks for making all field wiring electrical connections are located in a compartment identified as "Terminal Side" on the nameplate. The sensor terminals, power supply and signal-test terminals, as well as the zero and span adjustments are accessible by removing the Electronics Housing Cover (2) from the terminal side. The terminals are permanently attached to the housing and must not be removed.
- 2. The transmitter electronics Circuit Board Assembly (5, 6, 7) is located in a separate compartment, identified as "Circuit Side" on the nameplate. Make sure power is off. Then remove Circuit Side Cover (2).

NOTE

On the standard RTD input (Model 444RL), fast turn-on (Model 444RL _____B0912), and low-power (Models 444LL and LM) units, boards 5 and 6 are integrated into one board.

- 3. Remove the three Circuit Board Assembly Screws (4).
- 4. Push equally on the zero and span adjustment pot shafts from the terminal side. This will allow you to grasp and remove the Circuit Board Assembly.
- 5. If troubleshooting is required, it is best to keep the Circuit Board Assembly together for initial evaluation. Otherwise, the board assembly may be disassembled by grasping the Output Board (5) around its circumference and pulling it gently and evenly away from the other two boards. Remove the Amplifier Board (6) in the same manner. Take care not to bend the interconnection pins.
- 6. The adjustment pot shafts are sealed by two small O-rings (1D). Remove, if necessary, by taking off the O-ring Retainer Plate (1B), which is held in place by two small screws (1C).
- 7. The Nameplate (1E), Hazardous Service Certification Label (9), and Instrument Tag (8) are held in place with Drive Screws (1F). Remove any of these by gripping the head of the Drive Screw with pliers and carefully turning counter-clockwise.

Reassembly Procedure

AWARNING

Explosions can cause death or serious injury. Both transmitter covers must be fully engaged to meet explosion-proof requirements.

- 1. Inspect all O-rings (1D,3) and replace if necessary. Lightly grease new O-rings with silicone grease to guarantee an adequate seal.
- 2. If the O-ring Retainer Plate (1B) has been removed, be sure the correct side is facing outward. The resistor symbol should be visible on RTD Transmitters, while a thermocouple symbol should be visible on Thermocouple or Millivolt transmitters.
- 3. Inspect threaded connections on the housing and covers to make sure a minimum of five undamaged threads will be fully engaged. If the threads are shiny, apply a thin layer of molybdenum disulphide thread coating (such as Moly-Kote) to prevent galling of the aluminum threads.
- 4. If the Range Board (7A) requires a Coarse Zero Jumper (7B) check to make sure it is in the correct location for the desired temperature range. See Table 3-1, on page 3-3 or Table 3-2, on page 3-6.
- 5. Orient the Range Board (7A) and Amplifier Board (6) as shown in the Illustrated Parts List. Taking care not to bend the pins, plug the Amplifier Board into the Range Board. Press together until all three standoffs on the Amplifier Board rest against the Range Board.
- 6. Orient the Output Board (5) so its standoffs line up with the standoffs of the Amplifier/Range Board combination. Carefully and evenly, plug the output board into the Amplifier/Range Board. Take care not to bend the pins. Press together until all three standoffs on the Output Board rest against the Amplifier Board.
- 7. The circuit board assembly may be bench-tested, or calibrated outside the housing through the use of Test Terminal Strips (11 and 12). See the discussion of Calibration and Troubleshooting in this section.
- 8. If the circuit board assembly has been calibrated outside the housing, be very careful to ensure the zero and span adjustment pots are not moved while inserting the circuit board assembly into the housing.
- 9. Orient the circuit board assembly so the pot shafts line up with the pot holes in the housing.
- 10. Insert the circuit board assembly firmly into the housing.
- 11. Replace the three Circuit Board Assembly Screws (4).
- 12. Replace the transmitter covers (2). Tighten the covers hand-tight.

Interchangeability of Parts

AWARNING

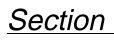
Use only the procedures and new parts specifically referenced in this manual. Unauthorized procedures or parts can affect product performance and the output signal used to control a process, and may render the instrument dangerous. Direct any questions concerning these procedures or parts to Rosemount Inc.

Rosemount Model 444 Alphaline Temperature Transmitters

Mechanical Parts	• All mechanical hardware is interchangeable among units without regard to model numbers.
	• Nameplates are interchangeable only among units that share the same input types (i.e. RTD, Thermocouple, or Millivolt).
Electrical Parts	• Amplifier Board: Interchangeable among Models 444T and 444M.
	• Output Board: 444T series (TE, TJ, TK, TT, TR, TS) and 444MV share a common output board.
	• Range Board: Interchangeable among units of the same input code (e.g., 444RL1).
Burnout Protection Adjustments	The Model 444T series (TE, TJ, TK, TT, TR, TS) and Model 444MV have a resistor network that drives the output either upscale or downscale if an open occurs in the input circuit. This option is identified in the model number. To convert from upscale to downscale, disassemble the circuit board assembly and remove R3 (22 meg, ¼WCC resistor) from the range board. To convert from downscale to upscale, replace R3. If no burnout protection is desired (as in some instances where the source has a high input impedance), remove both R2 and R3. See Figure 3-3, on page 3-6.
	Model 444RL has a jumper on the range board to select burnout protection. Placing the jumper in the "U" position will cause the output to be driven upscale if the RTD opens. If the jumper is in the "D" position the output will be driven downscale. See Figure 3-1, on page 3-3. Models 444LL and 444LM have inherent upscale burnout protection that cannot be changed. Model 444RL also has a jumper on the range board to specify mA output at the transmitter test terminals. Setting the jumper at the "V" position produces a 40–200 mV output at the test terminals. Setting the jumper at the "A" position produces a 4–20 mA output at the test terminals. See Figure 3-1, on page 3-4.
REPAIR AND WARRANTY SERVICE	Repair and warranty service is available through the Rosemount Regional Service Centers. Submit damage claims directly to the carrier.
RETURN OF MATERIALS	Exposure to hazardous substances can cause death or serious injury. If a hazardous substance is identified, a Material Safety Data Sheet (MSDS), required by law to be available to people exposed to specific hazardous substances, must be included with the returned materials.
	To expedite the return process, call the Rosemount North American Response Center toll-free at 800-654-RSMT (7768). This center, available 24 hours a day, will assist you with any needed information or materials.
	The center will ask for product model and serial numbers, and will provide a

The center will ask for product model and serial numbers, and will provide a Return Material Authorization (RMA) number. The center will also ask for the name of the process material the product was last exposed to.

The Rosemount North American Response Center will detail the additional information and procedures necessary to return goods exposed to hazardous substances.



FUNCTIONAL SPECIFICATIONS

5

Specifications and Reference Data

Inputs

Models 444RL, LL, and LM 100 Ω R_0 platinum RTD per IEC 751.

Model 444T

Thermocouple types E,J,K,T,R, and S per NIST (grounded or ungrounded).

Model 444MV

Millivolt input (grounded or ungrounded) source impedance less than 100 Ω.

R-numbers, specials

Special inputs other than standards, consult factory.

Spans

RTD	
Platinum	

Platinum	45 to 135 °F (25 to 75 °C). 125 to 380 °F (70 to 210 °C). 260 to 100 °F (70 to 210 °C).
Copper	360 to 1080 °F (200 to 600 °C). 180 to 540 °F (100 to 300 °C).
Nickel	45 to 360 °F (25 to 200 °C).

Thermocouples

Millivolt	
Type R, S	1467 to 3000 °F (815 to 1670 °C).
Type K	845 to 2540 °F (470 to 1410 °C).
Type K, E	504 to 1510 °F (280 to 840 °C).
Type J	504 to 1458 °F (280 to 810 °C).
Type J, K, E, T	180 to 540 $^{\circ}\mathrm{F}$ (100 to 300 $^{\circ}\mathrm{C}).$

Millivolt

5 to 15 mV. 15 to 45 mV.

Outputs

Linear with temperature for RTD inputs.

Linear with millivolt input signal for thermocouple or millivolt inputs; thermocouple and millivolt models input/output isolated to 500 V dc.

Models 444RL, T, MV 4-20 mA.

Model 444LL

0.8-3.2 V dc. Model 444LM 1.0-5.0 V dc.

Output Limits (approximate)

Models 444RL, T, MV

Low: 3.9 mA dc. High: 30.0 mA dc. **Model 444LL** Low: 0.1 V dc.

High: 4.2 V dc.

Model 444LM

Low: 0.125 V dc. High: 6.2 V dc.

Power Supply

Models 444RL, T, and MV

12 to 45 V dc at terminals of transmitter.

Model 444LL

5 to 12 V dc (overvoltage protected to 24 V dc) max current = 1.5 mA.

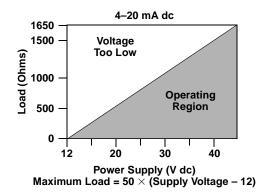
Model 444LM

8 to 12 V dc (overvoltage protected to 24 V dc) max current = 2.0 mA.

Load Limits

Models 444RL, T, and MV





Span and Zero

Continuously adjustable, as defined in the ordering table. Adjustments are accessible from the terminal side of the transmitter housing.

Transmitter Temperature Limits

–13 to 185 °F (–25 °C to 85 °C), transmitter operates within specifications.

-40 to 212 °F (-40 °C to 100 °C), transmitter operates without damage.

-58 to 248 °F (-50 °C to 120 °C), storage.

–13 to 149 °F (–25 °C to 65 °C), transmitter operates within specifications for meter option.

Loss of Input

Upscale burnout indication standard for RTD inputs, downscale burnout indication optional. Upscale burnout indication standard for thermocouple and millivolt inputs; downscale burnout indication or no indication optional.

Turn-on Time

2 seconds. No warm-up required.

PERFORMANCE SPECIFICATIONS

Accuracy

 $\pm 0.2\%$ of calibrated span (or, for thermocouple and millivolt inputs, ± 0.02 millivolts, whichever is greater). $\pm 0.5\%$ for copper, nickel, and isolated RTD inputs, 0.1% for differential RTD inputs. Includes combined effects of transmitter repeatability, hysteresis, linearity (conformity instead of linearity for thermocouple input), and adjustment resolution. Does not include sensor error.

Stability

 $\pm 0.2\%$ of calibrated span for six months.

Ambient Temperature Effect

Errors for 50 °F (28 °C) change in ambient temperature.

RTD Inputs

Zero: ±0.17 °C, *plus* Span: ±0.22%, *plus*

Elevation/Suppression: ±0.083% of base temperature in °C.

T/C Inputs (Includes Effect of Cold Junction)

Zero: ±1.38 °C, plus

Span: ±0.28% of span,

plus Elevation/Suppression: ±0.11% of base

temperature in °C.

Millivolt Inputs

Zero: ±0.038 mV,

plus

Span: ±0.28% of span, plus

Elevation/Suppression: ±0.11% of base input in mV.

Input Impedance (Thermocouple and mV Inputs)

More than 1 megohm—burnout resistors disconnected.

Power Supply Effect

±0.005% per volt.

Load Effect

No load effect other than the change in voltage supplied to the transmitter.

Vibration Effect

 $\pm 0.05\%$ of span per g to 200 Hz in any axis for 3 g's up to 33 Hz, 2 g's from 33 to 70 Hz and 1 g from 70 to 200 Hz.

Mounting Position Effect

None.

PHYSICAL	Material
SPECIFICATIONS	Electro Low-co
	Housi

aterials of Construction Electronics Housing Low-copper aluminum. (NEMA 4X). IP 54, IP 65, IP 66.

Housing Paint Polyurethane.

Housing O-rings

Buna-N.

Sensor and Conduit Connections

¹/2-inch conduit on electronics housing. Screw terminals and integral test jacks compatible with miniature banana plugs (Pomona 2944, 3690 or equal).

Weight

Transmitter: 3 lb (1.4 kg).

Transmitter with mounting bracket: 4 lb (1.8 kg).

Hazardous Location Certifications

Factory Mutual (FM) Approvals

E5 Explosion Proof: Class I, Division 1, Groups B, C, and D. Dust Ignition Proof: Class II, Division 1, Groups E, F, and G; Class III, Division 1 hazardous locations. Indoor and outdoor use. NEMA Enclosure Type 4X.

Refer to Factory Mutual Explosion Proof Drawing 00444-0261.

I5 Intrinsic Safety: Class I, Division 1, Groups A, B, C, and D; Class II, Division 1, Groups E, F, and G; Class III, Division 1 hazardous locations; Intrinsically safe system only when applying Table 5-1 entity parameters. Nonincendive: Class I, Division 2, Groups A, B, C, and D; Indoor and outdoor use. NEMA Enclosure Type 4X.

Refer to Factory Mutual Intrinsic Safety Drawing 01151-0214.

K5 Combination of E5 and I5.

TABLE 5-1.	FΜ	Entity
Parameters.		

Model 444 Parameters	Associated Equipment Parameters	FM Approved for Class I, II, III, Division 1, Groups		
	Farameters	Α	В	C thru G
$V_{MAX} = 40 V$ $I_{MAX} = 165 mA$ $C_i = 0.044 \mu F$ $L_i = 0$	$V_{OC} \text{ or } V_T \leq 40 \text{ V}$ $I_{SC} \text{ or } I_T \leq 165 \text{ mA}$ $C_A > 0.044 \mu\text{F}$ $L_A > 0$	•	•	•
$V_{MAX} = 40 V$ $I_{MAX} = 225 mA$ $C_i = 0.044 \mu F$ $L_i = 0$	$V_{OC} \text{ or } V_T \leq 40 \text{ V}$ $I_{SC} \text{ or } I_T \leq 225 \text{ mA}$ $C_A > 0.044 \mu \text{F}$ $L_A > 0$	NA	NA	•

Canadian Standards Association (CSA) Approvals

- **E6** Explosion Proof: Class I, Division 1, Groups C and D; Dust-ignitionproof Class II, Division 1, Groups E, F, and G; Class III, Division 1 hazardous locations; Suitable for Class I, Division 2, Groups A, B, C, and D; CSA Enclosure Type 4X.
- **16** Intrinsic Safety: Class I, Division 1, Groups A, B, C, and D. Intrinsically safe system only when applying Table 5-2 parametric parameters. Temperature code T2D. CSA Enclosure Type 4X.

Refer to CSA Intrinsic Safety Drawing 00444-0034.

C6 Combination of E6 and I6.

TABLE 5-2. CSA Parametric Parameters.

Barrier Manufacturer/Model	CSA Approved for Class I, Division 1 Groups			
	Α	В	С	D
Any CSA approved zener barrier $\leq 30 \text{ V}, \geq 330 \Omega \text{ or}$ $\leq 28 \text{ V}, \geq 300 \Omega \text{ or}$ $\leq 22 \text{ V}, \geq 180 \Omega$	•	•	•	•
Foxboro Converters 2AI-I2V-CGB 2AI-I3V-CGB 2AS-I2I-CGB 3AD-I3IA CS-E/CGB-A 3A2-I2D CS-E/CGB-A, 3A2-I3D CS-E/CGB-A 3A4-I2DA CS-E/CGB-A 3F4-I2DA1 CS-E/CGB-A	NA	•	•	•
Any CSA approved zener barrier \leq 30 V, \geq 150 Ω	NA	NA	•	•

Standards Association of Australia (SAA) Certifications

E7 Flameproof:

Ex d IIB+H2 T6

Class I, Zone 1. DIP T6

Class II.

Special Conditions for Safe Use ("X"):

For transmitters having NPT or PG cable entry thread, an appropriate flameproof thread adaptor shall be used to facilitate application of certified flameproof cable glands. Only SAA-certified flameproof temperature sensors shall be used with the Model 444 Temperature Transmitter if fitted directly into the tapped entry of the enclosure.

I7 Intrinsic Safety:

Ex ia IIC T6 ($T_{amb} = 40$ °C) Ex ia IIC T5 ($T_{amb} = 70$ °C) Class I, Zone 0 Entity Parameters: $U_i = 30$ V $I_i = 200$ mA $P_i = 1.0$ W $C_i = 0.024 \mu F$ $L_i = 0$

Refer to SAA Intrinsic Safety Drawing 00444-0264.

Special Conditions for Safe Use ("X"):

The equipment has been assessed to the "Entity" concept and upon installation the barrier/entity parameters must be taken into account.

N7 Type "n":

Ex n IIC T6 (T_{amb} = 40 °C) Ex n IIC T5 (T_{amb} = 70 °C) Class I, Zone 2

Special Conditions for Safe Use ("X"):

The equipment must be connected to a supply voltage which does not exceed the rated voltage. The enclosure end caps must be correctly fitted while the equipment is powered.

Centro Elettrotecnico Sperimentale Italiano (CESI/CENELEC) Certifications E8 Flameproof:

EEx d IIC T6

18 **Intrinsic Safety:** Model 444RL EEx ia IIC T6 ($T_{amb} = 40 \text{ °C}$) [$P_i = 0.75 \text{ W}$] EEx ia IIC T5 ($T_{amb} = 55 \text{ °C}$) [$P_i = 1.0 \text{ W}$] EEx ia IIC T4 ($T_{amb} = 80 \text{ °C}$) [$P_i = 1.0 \text{ W}$] Model 444T & MV $\begin{array}{l} \mathrm{EEx\ ib\ IIB\ T6\ }(\mathrm{T_{amb}}=40\ ^{\circ}\mathrm{C})\ [\mathrm{P_{i}}=0.75\ \mathrm{W}] \\ \mathrm{EEx\ ib\ IIB\ T5\ }(\mathrm{T_{amb}}=55\ ^{\circ}\mathrm{C})\ [\mathrm{P_{i}}=1.0\ \mathrm{W}] \\ \mathrm{EEx\ ib\ IIB\ T4\ }(\mathrm{T_{amb}}=80\ ^{\circ}\mathrm{C})\ [\mathrm{P_{i}}=1.0\ \mathrm{W}] \end{array}$ **Entity Parameters:** $V_{i} = 30 V dc$ $I_i = 200 \text{ mA}$ $P_i = 0.75 \text{ W} (T6)$ $P_i = 1.0 W (T5)$ $P_i = 1.0 \text{ W} (T4)$ $C_i = 0.024 \ \mu F (Model 444RL)$ $C_i = 0.006 \ \mu F \ (Model \ 444T_ \& \ MV)$ $L_{i} = 0.$

Special Conditions for Safe Use ("X"):

If the temperature sensor connected to the input circuit does not tolerate an alternating tension of 500V for 60 seconds, the certified transducers must be powered by galvanically-insulated equipment. Model 444RL temperature transducers must be connected to associated electronic equipment certified to EN 50.014/EN 50.020 standards.

British Approvals Service for Electrical Equipment Flammable Atmospheres (BASEEFA) Type N Certification

N1 Ex N II T5

Maximum Voltage: 35 V dc Maximum Current: 30 mA dc

An appropriate stainless steel tag will be supplied according to the certification option selected.

LCD METER SPECIFICATIONS (OPTIONS D AND E)

Functional	Configuration 4 mA point limits: –999 to 1000.
Specifications	-
	Span limits: 0200 to 9999.
	The sum of the 4 mA point and span must not exceed 9999. Adjustments are made using non-interactive zero and span buttons.
	Temperature Limits
	Storage: -40 to 85 °C (-40 to 185 °F).
	Operating: -20 to 70 °C (-4 to 158 °F).
	Between –40 to –20 °C (–40 to –4 °F) loop is intact and the meter is not damaged.
	Humidity Limitation
	0 to 95% non-condensing relative humidity.
	Update Period
	750 ms.
	Response Time
	Responds to changes in input within a maximum of two update periods. If the filter is activated, then the display responds to the change within nine update periods.
Performance	Digital Display Resolution
Specifications	0.05% of calibrated range ±1 digit.
	Analog Bar Graph Resolution
	0.05% of calibrated range.
	Indication Accuracy
	0.25% of calibrated range ± 1 digit.
	Stability
	Over Time: 0.1% of calibrated range ±1 digit per six months.
	Temperature Effect
	0.01% of calibrated range per °C on zero.
	0.02% of calibrated range per °C on span over the operating temperature range.
	Power Interrupt
	All calibration constants are stored in EEPROM memory and are not affected by power loss.
	Failure Mode
	LCD meter failure will not affect transmitter operation.
	Under/Over Range Indication
	Input current < 3.5 mA: Display blank.
	Input current > 22.0 mA: Display flashes 112.5% of full scale value or 9999, whichever is less.
Physical	Meter Size
Specification	$2\frac{1}{2}$ -inch diameter face with four, $\frac{1}{2}$ -inch high characters.

ANALOG METER SPECIFICATIONS (OPTIONS B AND C)

Functional	Meter Indication
Specifications	0 to 100% linear scale.
	Special optional ranges.
	Temperature Limits
	-40 to 65 °C (-40 to 150 °F).
	Humidity Limits
	0 to 100% relative humidity.
	Zero Adjustment
	Adjustment screw on face of meter.
Performance	Indication Accuracy
Specifications	±2% of calibrated span.
	Temperature Effect
	Less than 2% of full scale at any point within the temperature limits.
Physical	Meter Size
Specification	2 ¹ / ₄ -inch diameter face with 2-inch long scale.

TABLE 5-3. 444 Model Structure.

Model	Product Descriptio							
444	Alphaline Temperatur							
Code	Input Type ⁽¹⁾	Temp Minimum	erature Span Maximum	Base Te Minimum	mperature Maximum	Upper Range Limi		
RL1	Platinum RTD	45 °F (25 °C)	135 °F (75 °C)	–58 °F (–50 °C)	300 °F (150 °C)	435 °F (225 °C)		
RL2	100 Ω R ₀	125 °F (70 °C)	380 °F (210 °C)	–58 °F (–50 °C)	300 °F (150 °C)	680 °F (360 °C)		
RL3	linearized output	360 °F (200 °C)	1080 °F (600 °C)	–58 °F (–50 °C)	300 °F (150 °C)	1380 °F (750 °C)		
RL9	Special Input, Range	or Accuracy (minimum	span 3 Ω)					
	Thermocouple		· · ·					
TJ1	Type J	180 °F (100 °C)	540 °F (300 °C)	–58 °F (–50 °C)	300 °F (150 °C)	840 °F (450 °C)		
TJ2	Type J	504 °F (280 °C)	1458 °F (810 °C)	–58 °F (–50 °C)	930 °F (500 °C)	1400 °F (760 °C)		
TK1	Туре К	180 °F (100 °C)	540 °F (300 °C)	–58 °F (–50 °C)	300 °F (150 °C)	840 °F (450 °C)		
TK2	Туре К	504 °F (280 °C)	1510 °F (840 °C)	–58 °F (–50 °C)	930 °F (500 °C)	2440 °F (1340 °C)		
TK3	Туре К	845 °F (470 °C)	2540 °F (1410 °C)	–58 °F (–50 °C)	930 °F (500 °C)	2500 °F (1370 °C)		
TE1	Туре Е	180 °F (100 °C)	540 °F (300 °C)	–58 °F (–50 °C)	300 °F (150 °C)	840 °F (450 °C)		
TE2	Туре Е	504 °F (280 °C)	1510 °F (840 °C)	–58 °F (–50 °C)	930 °F (500 °C)	1830 °F (1000 °C)		
TT1	Туре Т	180 °F (100 °C)	540 °F (300 °C)	–58 °F (–50 °C)	300 °F (150 °C)	750 °F (400 °C)		
TR1	Type R	1467 °F (815 °C)	3000 °F (1670 °C)	0 °F (–18 °C)	1500 °F (815 °C)	3200 °F (1760 °C)		
TS1	Type S	1467 °F (815 °C)	3000 °F (1670 °C)	0 °F (–18 °C)	1500 °F (815 °C)	3200 °F (1760 °C)		
T_9	Special Range or Acc	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	mV, maximum span 100	,				
MV1	Millivolt	5 mV	15 mV	-2 mV	8 mV	23 mV		
MV2	Millivolt	15 mV	45 mV	-2 mV	20mV	65 mV		
MV9			mV, maximum span 100	mV)				
Code	Loss of Input Indic	ation						
U	Upscale (standard for	all input types)						
D	Downscale							
N	None (not available for	r platinum RTD inputs)						
Code	Calibration							
1	Trim to IEC 751 Class	B (RTD) or NIST Curve	e (thermocouple)					
2	Trim to Specific Mode	I 68/78/88 Calibration S	chedule					
3	Trim to Other Nomina	I Curve (customer must	specify separately) (Note:	Millivolt input must use	Code 3.)			
Code	Meter Options							
A B	None Integral Analog Motor	, Special Scale (same a	e calibrated range)					
C	Integral Analog Meter		is calibrated farige)					
D	Integral LCD Meter, 0							
E			nge, mode, and engineeri	(1)				
Code	Mounting Bracket	pecial Ocale (Specify 1a						
	-							
1 2	None Mounting Bracket for 1	2-inch Pipe or Surface N	Jounting					
2 Code	Hazardous Area Ce		Nounting					
NA	No Certification Requ							
E5	FM Explosion-Proof A							
15		d Non-incendive Appro	val					
E6								
16	CSA Explosion-Proof Approval CSA Intrinsic Safety Approval (444RL and 444T only)							
E7	SAA Explosion-Proof Certification							
17	SAA Intrinsic Safety C							
N7	SAA Non-incendive C							
E8			dering a transmitter with th	is option, place a W bef	ore the model number: V	V444.)		
18	CESI Intrinsic Safety	Certification (When orde	ering a transmitter with this	s option, place a W befo	re the model number: W	444.)		
N1	BASEEFA Non-incent	dive Certification (When	ordering a transmitter wit	h this option, place a T b	pefore the model number	r: T444.)		
Code	Options							
Q4	2-Point Calibration Ce	ertificate						
A1		0 (CM 20) SST Thread	Adapter					
	. ,	0 (CM 20) SST Thread						
A2								
	Special							
A2 Code	Special	ith RL9, T_9, and MV9	ipputs)					

(1) Refer to Temperature Sensors, Assemblies , and Accessories Product Data Sheet, Rosemount pub. no. 00813-0100-2654 for information about Rosemount sensor assemblies.

(2) LCD Meters are only available with RL1, RL2, or RL3. (may be reconfigured in the field.)

TABLE 5-4. 444RL Fast Turn-on Model Structure.

Model	Product Description							
444	Alphaline Fast Turn-On Temperature Transmitter							
Code	Input Type ⁽¹⁾	Temperat Minimum	ure Span Maximum	Base Temperat Minimum	Base Temperature (4mA Point) Minimum Maximum			
RL1 RL2 RL3	$\begin{array}{c} \textbf{Platinum RTD} \\ 100 \ \Omega \ \textbf{R}_0 \\ \textbf{linearized output} \\ \textbf{linearized output} \end{array}$	45 °F (25 °C) 125 °F (70 °C) 360 °F (200 °C)	135 °F (75 °C) 380 °F (210 °C) 1080 °F (600 °C)	–58 °F (–50 °C) –58 °F (–50 °C) –58 °F (–50 °C)	300 °F (150 °C) 300 °F (150 °C) 300 °F (150 °C)	435 °F (225 °C 680 °F (360 °C 1380 °F (750 °l		
Code	Loss of Input Indi	cation						
U	Upscale (standard for	or all input types)						
Code	Calibration							
1 2 3	Trim to Specific Mod	Trim to IEC 751 Curve (RTD) Trim to Specific Model 68/78/88 Calibration Schedule Trim to Other Nominal Curve (customer must specify separately)						
Code	Meter Options							
A B C	None Integral Analog Mete Integral Analog Mete	er, Special Scale (must s er, 0–100% Scale	pecify range, mode, and	d engineering units)				
Code	Mounting Bracket							
1 2	None Mounting Bracket for 2-inch Pipe or Surface Mounting							
Code	Hazardous Area Certifications							
NA E5 E6 I6	No Certification Req FM Explosion-Proof CSA Explosion-Proo CSA Intrinsic Safety	Approval of Approval						
Code	Options							
Q4 A1 A2		rtificate 0 (CM 20) SST Thread Ac 0 (CM 20) SST Thread Ac						
Code	Special							
B0912	Fast Turn-on Electro	nics						

(1) Refer to Temperature Sensors, Assemblies, and Accessories Product Data Sheet, Rosemount pub. no. 00813-0100-2654 for information about Rosemount sensor assemblies.

TABLE 5-5. 444LL, LM Model Structure.

Model	Product Description				
444	Alphaline Low-Power Temperature Tran	nsmitter			
Code	Input Type ⁽¹⁾	Temperatu Minimum	ure Span Maximum	Base Temperatu Minimum	ire (4mA Point) Maximum
LL1 LM1	Platinum RTD 100 Ω R ₀ Linearized Output	75 °F (42 °C) 75 °F (42 °C)	150 °F (83 °C) 150 °F (83 °C)	–25 °F (–32 °C) –25 °F (–32 °C)	
Code	Loss of Input Indication				
U	Upscale				
Code	Calibration				
1 2	Trim to IEC 751 Curve (RTD) Trim to Specific Model 68/78/88 Calibra	ation Schedule			
Code	Meter Options				
А	None				
Code	Mounting Bracket				
1 2	None Mounting Bracket for 2-inch Pipe or Su	rface Mounting			
Code	Options				
NA E5 E6 I6	No Certification Required FM Explosion-Proof Approval CSA Explosion-Proof Approval CSA Intrinsic Safety Approval (444RL a	and 444T only)			

(1) Refer to Temperature Sensors, Assemblies , and Accessories Product Data Sheet, Rosemount pub. no. 00813-0100-2654 for information about Rosemount sensor assemblies.

TABLE 5-6. Meter Kits.

Part Description	Part Number	Spares Category ⁽¹⁾
40–200 mV Analog Meter Kit ⁽²⁾	00444-0194-0001	С
40–200 mV Analog Meter Kit (CENELEC and I.S. approved) (2)	00444-0194-0005	С
40-200 mV Analog Meter	01151-0687-0003	С
40-200 mV Analog Meter (CENELEC approved)	01151-0744-0003	С
4–20 mA LCD Meter Kit ^{(2) (3)}	00444-0194-0004	С
4–20 mA LCD Meter	01151-1300-1000	С
Mounting Hardware and Cover Kit	00444-0194-0002	С
Mounting Hardware Kit	00444-0194-0003	С
Cover Assembly	01151-2610-0001	С
Meter with Special Scale ⁽⁴⁾	scale: XX to XX	С

(1) Normally, no spare parts required for C classification.

(2) Meter kit includes meter, mounting hardware, and cover assembly.

(3) LCD Meters are only available with RL1, RL2, and RL3 (may be reconfigured in the field).

(4) For Special Scale Meters, order appropriate meter and indicate special scale desired. Mounting hardware and cover assembly must be ordered separately

TABLE 5-7. Standard Parts List.

ltem Number	Model	Part Description	Part Number	Spares Category ⁽¹⁾
1	444R 444T 444M	Housing Kit—RTD Input Housing Kit—Thermocouple Input Housing Kit—Millivolt Input Electronics housing kit consists of: 1 each electronics housing (item (^A)) 1 each O-ring retainer plate (item (^B)) 2 each 6–32 \times ³ /16 retainer plate screws (item (^C)) 2 each pot O-rings (item (^D)) 1 each nameplate (item (^E)) 2 each #4–40 \times ³ /16 screws (item (^E))	00444-0028-0001 00444-0028-0002 00444-0028-0003	C C C
2	ALL	Housing Cover—Quantity One	90032-0240-0003	С
3	ALL	Housing Cover O-ring	01151-0033-0003	С
Ð	ALL	Adjustment Potentiometer O-ring (pkg. of 12)	00444-0030-0001	В
4	ALL	Electronics Assembly Screws, $6-32 \times 1^7/8$ (pkg. of 12)	00444-0031-0001	С
3	ALL	Cover O-rings. (pkg. of 12)	00444-0030-0001	В
5	ALL	A/O Board—RTD Input (2 board set, Figure 5-1) Output Board—T/C, mV Input (3 board set, Figure 5-2)	00444-0228-0001 00444-0015-0001	A A
6	ALL	Amplifier Board—All Inputs (3 board set, Figure 5-2)	00444-0007-0003	А
TA)	444R	Range Board—RTD Inputs 25 to 75 °C Span (Input Code RL1) 70 to 210 °C Span (Input Code RL2) 200 to 600 °C Span (Input Code RL3) Special Range RL9 (requires 3 board set – consult factory)	00444-0221-0001 00444-0221-0002 00444-0221-0003 00444-0003-XXXX	A A A
æ	444T	Range Board—Thermocouple Inputs Type J, 100 to 300 °C Span (Input Code TJ1) Type J, 280 to 840 °C Span (Input Code TJ2) Type K, 100 to 300 °C Span (Input Code TK1) Type K, 280 to 840 °C Span (Input Code TK2) Type K, 470 to 1410 °C Span (Input Code TK3) Type E, 100 to 300 °C Span (Input Code TE1) ⁽²⁾ Type E, 280 to 840 °C Span (Input Code TE2) Type T, 100 to 300 °C Span (Input Code TE1) Type R, 815 to 1670 °C Span (Input Code TR1) Type S, 815 to 1670 °C Span (Input Code TS1) Special Range T-9 Kit (consult factory)	00444-0262-0002 00444-0262-0006 00444-0262-0003 00444-0262-0007 00444-0262-0008 00444-0262-0001 00444-0262-0005 00444-0262-0009 00444-0262-0010 00444-0013-XXXX	A A A A A A A A A
(7A)	444M	Range Board—Millivolt Inputs 5 to 15 mV (Input Code MV1) 15 to 45 °C Span (Input Code MV2) Special Range MV9 (consult factory)	00444-0023-0001 00444-0023-0002 00444-0023-XXXX	A A A
7B	444R	Range Board Zero Jumpers (pkg. of 12)	00444-0036-0001	A
8	ALL	Instrument Tag (optional)	01151-0148	С
9	ALL	Certification Label	_	С
10	ALL	Mounting Bracket Kit 1 each mounting bracket (item $(0A)$) 4 each $\frac{1}{2}-20 \times \frac{1}{2}$ bolts(item $(0B)$) 2 each U-bolts (item $(10C)$) 4 each $\frac{1}{2}$ washers (item $(10D)$) 4 each $\frac{5}{16}-18$ nuts (item $(10D)$) 2 each washer plates (item $(10D)$)	00444-0022-0001	С
(1) (12)	ALL	Terminal Block, Three-position Terminal Block, Four-position	C10448-0106 C10448-0109	D D

(1) Spares Categories (2) Thermocouple Range Board Kit Consists of:

Code A – Recommended 1 spare part per 25 transmitters. 1 each T/C Range Board. Code B – Recommended 1 spare part per 50 transmitters. 1 each External CJC Block. Code C – None normally required.

Code D – Not used on transmitters, but recommended for repair activities.

TABLE 5-8.	Parts List for Model W444	Transmitter (CESI/CENELE)	C Approval).
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ltem Number	Part Description	Part No.	Spares Category ⁽¹⁾
1	Housing Kit ⁽²⁾ — RTD Input	00444-0028-0001	С
	Housing Kit ⁽²⁾ — Thermocouple Input	00444-0028-0002	С
	Housing kit ⁽²⁾ — Millivolt Input	00444-0028-0003	С
2	Housing Cover—Quantity One	90032-0240-0003	С
3	Housing Cover O-rings	01151-0033-0003	В
	Adjustment Potentiometer O-rings	00444-0030-0001	В
4	Electronics Assembly Screws	00444-0031-0001	С
(5)	A/O Board—RTD Input	00444-0228-0001	А
Ŭ	Output Board—T/C, mV Input	00444-0015-0002	А
	Output Board—RD Input	00444-0111-0001	А
6	Amplifier Board	00444-0007-0003	A
	Range Board W444 RL1 W444 RL2 W444 RL3 W444 RL9 (consult factory) W444 TJ1 W444 TJ2 W444 TK1 W444 TK2 W444 TK3 W444 TE1 W444 TE1 W444 TS1 W444 TS1 W444 TS1 W444 TS1 W444 WV1 W444 MV2 W444 MV2 W444 MV9 (consult factory)	00444-0221-0001 00444-0221-0002 00444-0221-0003 00444-0262-0002 00444-0262-0002 00444-0262-0006 00444-0262-0003 00444-0262-0007 00444-0262-0001 00444-0262-0001 00444-0262-0004 00444-0262-0009 00444-0262-0010 00444-0023-0001 00444-0023-0002 00444-0023-XXXX	A A A A A A A A A A A A A A A A A A A
(7B)	Range Board Zero Jumpers	00444-0036-0001	A
10	Mounting Bracket Kit	00444-0022-0001	С
(1) (12)	Terminal Block, Three-position Terminal Block, Four-position	C10448-0106 C10448-0109	D

(1) Spares Categories Code A – Recommended one spare part per 25 transmitters.

Code B – Recommended one spare part per 50 transmitters.

Code C – None normally required. Code D – Not used on transmitters, but recommended for repair activities (see Instruction Manual).

(2) Housing kit includes housing, adjustment potentionmeter O-rings, O-ring retainer plate and nameplate.

Rosemount Model 444 Alphaline Temperature Transmitters

TABLE 5-9. Parts List for Model T444 Transmitter (BASEEFA Approval).

ltem Number	Part Description	Part No.	Spares Category ⁽¹⁾
1	Housing Kit ⁽²⁾ —RTD Input	00444-0028-0001	С
	Housing Kit ⁽²⁾ —Thermocouple Input	00444-0028-0002	С
	Housing kit ⁽²⁾ —Millivolt Input	00444-0028-0003	С
2	Housing Cover—Quantity One	90032-0240-0003	С
3	Housing Cover O-rings	01151-0033-0003	В
	Adjustment Potentiometer O-rings	00444-0030-0001	В
4	Electronics Assembly Screws	00444-0031-0001	С
(5)	A/O Board—RTD Input	00444-0228-0001	Α
\bigcirc	Output Board—T/C, mV Input	00444-0015-0001	
6	Amplifier Board	00444-0007-0003	А
(7A)	Range Boards		
	T444 RL1	00444-0136-0001	A
	T444 RL2	00444-0136-0002	A
	T444 RL3	00444-0136-0003	A
	T444 RL9 (consult factory)	00444-0136-XXXX	A
	T444 TE1	00444-0273-0001	A
	T444 TJ1	00444-0273-0002	A
	T444 TK1	00444-0273-0003	A
	T444 TT1	00444-0273-0004	А
	T444 TE2	00444-0273-0005	A
	T444 TJ2	00444-0273-0006	A
	T444 TK2	00444-0273-0007	A
	T444 TK3	00444-0273-0008	A
	T444 TR1	00444-0273-0009	A
	T444 TS1	00444-0273-0010	A
	T444 T_9 (consult factory)	00444-0138-XXXX	A
	T444 MV1	00444-0139-0001	А
	T444 MV2	00444-0139-0002	A
	T444 MV9 (consult factory)	00444-0139-XXXX	А
7B	Range Board Zero Jumpers	00444-0036-0001	А
10	Mounting Bracket Kit	00444-0022-0001	С
(1)	Terminal Block, Three-position	C10448-0106	D
12	Terminal Block, Four-position	C10448-0109	D

For meter information, see page 7.

(1) Spares Categories

Code A – Recommended one spare part per 25 transmitters. Code B – Recommended one spare part per 50 transmitters. Code C – None normally required. Code D – Not used on transmitters, but recommended for repair activities (see Instruction Manual).

(2) Housing kit includes housing, adjustment potentiometer O-rings, O-ring retainer plate and nameplate.

TABLE 5-10. Parts List for Model 444 RL Fast Turn On Transmitter (RTD Input).

ltem Number	Part Description	Part No.	Spares Category ⁽¹⁾
1	Housing Kit ⁽²⁾	00444-0028-0001	С
2	Housing Cover—Quantity One	90032-0240-0003	С
3	Housing Cover O-rings	01151-0033-0003	В
	Adjustment Potentiometer O-rings	00444-0030-0001	В
4	Electronics Assembly Screws	00444-0031-0001	С
5	Output Board 444 RL B0912	00444-0126-0001	A
(7A)	Range Boards RL1 B0912 RL2 B0912 RL3 B0912	00444-0221-0011 00444-0221-0012 00444-0221-0013	A A A
7B	Range Board Zero Jumpers	00444-0036-0001	A
10	Mounting Bracket Kit	00444-0022-0001	С
(1) (12)	Terminal Block, Three-position Terminal Block, Four-position	C104480106 C104480109	D D

For meter information, see page 7.

(1) Spares Categories

Code A – Recommended one spare part per 25 transmitters.

Code B – Recommended one spare part per 50 transmitters.

Code C – None normally required.

Code D – Not used on transmitters, but recommended for repair activities (see Instruction Manual).

(2) Housing kit includes housing, adjustment potentiometer O-rings, O-ring retainer plate and nameplate.

TABLE 5-11. Parts List for Model 444 LL, 444 LM Low Power Transmitter (RTD Input).

ltem Number	Part Description	Part No.	Spares Category ⁽¹⁾
1	Housing Kit ⁽²⁾	00444-0028-0005	С
2	Housing Cover—Quantity One	90032-0240-0003	С
3	Housing Cover O-rings	01151-0033-0003	В
	Adjustment Potentiometer O-rings	00444-0030-0001	В
4	Electronics Assembly Screws	00444-0031-0001	С
5	Output Board 444 LL Output Board 444 LM	00444-0159-0001 00444-0159-0002	A A
(7A)	Range Boards 444 LL 444 LM	00444-0157-0001 00444-0157-0002	A A
7B	Range Board Zero Jumpers	00444-0036-0001	С
10	Mounting Bracket Kit	00444-0022-0001	С
(11) (12)	Terminal Block, Three-position Terminal Block, Four-position	C104480106 C104480109	D D

No meter available.

(1) Spares Categories

Code A – Recommended one spare part per 25 transmitters.

Code B – Recommended one spare part per 50 transmitters.

Code C – None normally required.

Code D – Not used on transmitters, but recommended for repair activities (see Instruction Manual).

(2) Housing kit includes housing, adjustment potentiometer O-rings, O-ring retainer plate and nameplate.

TABLE 5-12. Parts List for Model 444 Increased Accuracy or Special Range Transmitters.

ltem Number	Part Description	Part No.	Spares Category ⁽¹⁾
1	Housing Kit ⁽²⁾ —RTD Input Housing Kit ⁽²⁾ —Thermocouple Input Housing kit ⁽²⁾ —Millivolt Input	00444-0028-0001 00444-0028-0002 00444-0028-0003	000
2	Housing Cover—Quantity One	90032-0240-0003	С
3	Housing Cover O-rings	01151-0033-0003	В
	Adjustment Potentiometer O-rings	00444-0030-0001	В
4	Electronics Assembly Screws	00444-0031-0001	С
5	Output Board RL9 Output Board T_9 Output Board MV9	00444-0005-0001 00444-0015-0001 00444-0015-0001	A A A
6	Amplifier Board	00444-0007-0003	А
TA	Range Boards RL9 (consult factory) T_9 (consult factory) MV9 (consult factory)	00444-0003-XXXX 00444-0013-XXXX 00444-0023-XXXX	A A A
7B	Range Board Zero Jumpers	00444-0036-0001	С
10	Mounting Bracket Kit	00444-0022-0001	С
(1) (12)	Terminal Block, Three-position Terminal Block, Four-position	C10448-0106 C10448-0109	D D

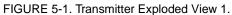
For meter information, see below.

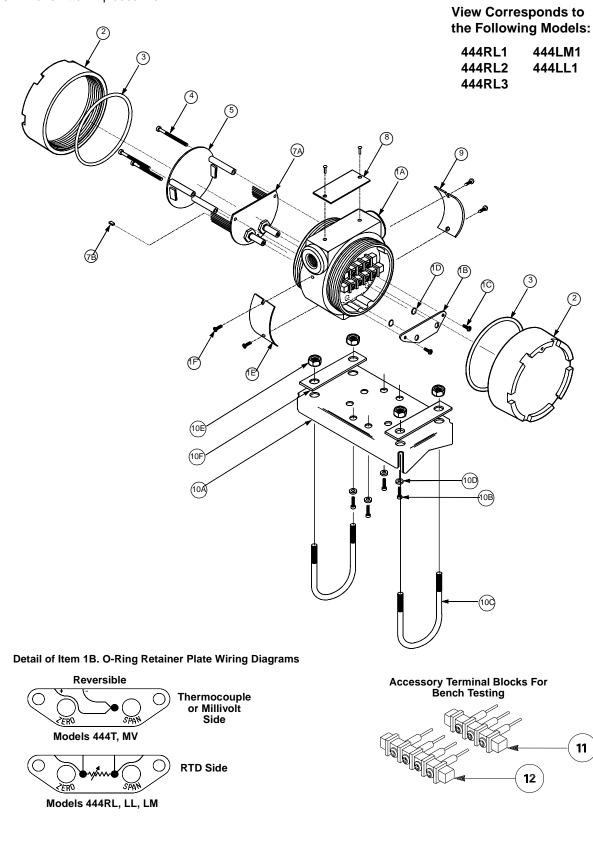
(1) Spares Categories

Code A – Recommended one spare part per 25 transmitters. Code B – Recommended one spare part per 50 transmitters.

Code C – None normally required.

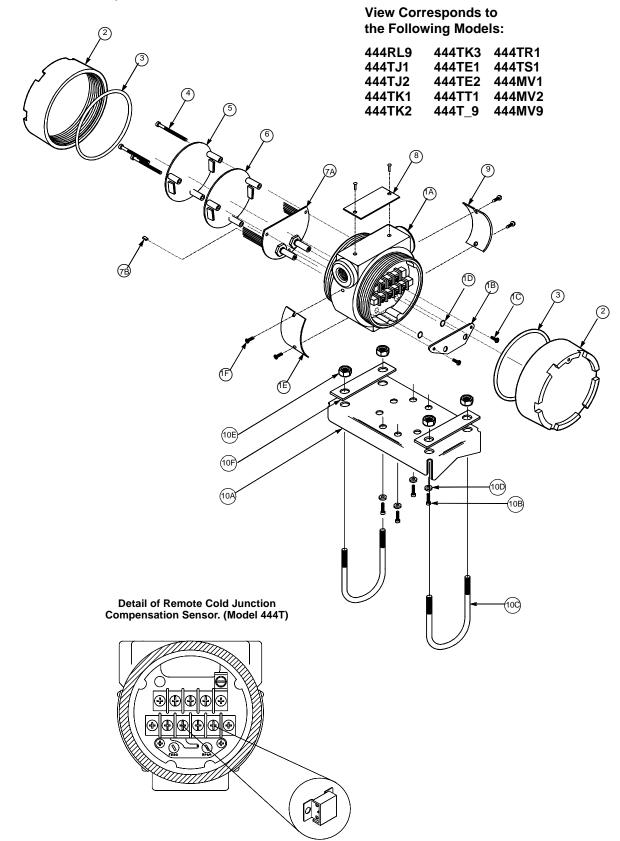
Code D – Not used on transmitters, but recommended for repair activities.
(2) Housing kit includes housing, adjustment potentiometer O-rings, O-ring retainer plate and nameplate.





444-1151C02A, 0071A01A, 0071B01A, 1151H02A

FIGURE 5-2. Transmitter Exploded View 2.





Options

MOUNTING BRACKET

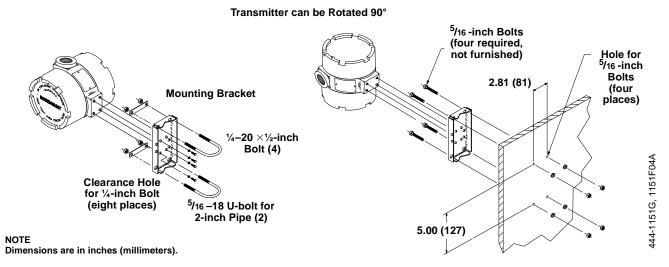
6

The mounting bracket option provides auxiliary configurations for mounting the Model 444 transmitter. With this option you can either mount the transmitter to a 2-inch pipe or a suitable flat panel. The bracket is constructed of carbon steel with carbon steel U-bolts. See Figure 6-1 for an exploded view of the Model 444 with a mounting bracket in both configurations.

FIGURE 6-1. Model 444 with Optional Mounting Bracket.

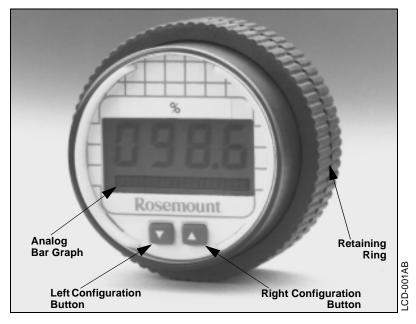
PIPESTAND MOUNTING

PANEL OR SURFACE MOUNTING



LCD / ANALOG
METERThe LCD and analog meters provide local indication of the transmitter output.
Both meters attach easily to the terminal side of the transmitter.LCD METERThe Rosemount® LCD meter plugs directly into the Model 444 to provide a
highly accurate digital display of the process variable. The meter adds no voltage
drop in the 4–20 mA current loop when connected directly across the transmitter
test terminals.ConfigurationConfigure the LCD meter to meet specific requirements by using the left and
right calibration buttons located on the meter face as shown in Figure 6-2. The
analog bar graph is also shown in Figure 6-2. The 20-segment bar graph is
factory calibrated and represents
4–20 mA directly.

FIGURE 6-2. LCD Meter.



No calibration equipment is required to configure the LCD meter, but between 4 and 20 mA must exist in the loop in order for the meter to operate. The actual value of the current is not significant. In addition, meter configuration does not affect the transmitter/loop current. Use the following meter configuration procedure to properly configure the LCD meter.

Remove the Cover

1. Unscrew the retaining ring shown in Figure 6-2 and lift the transparent cover off of the housing.

NOTE

The LCD meter time-out is approximately 16 seconds. If keys are not pressed within this period, the indicator reverts to reading the current signal.

Position the Decimal Point and Select the Meter Function

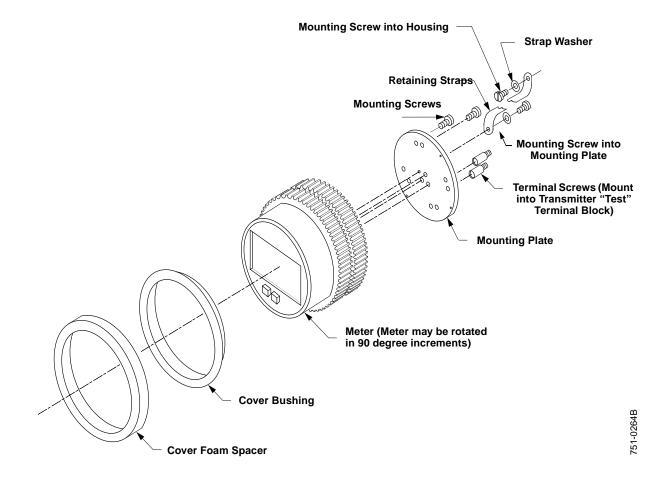
- 2. Press the left and right configuration buttons simultaneously and release them immediately.
- 3. To move the decimal point to the desired location, press the left configuration button. Note that the decimal point wraps around.
- 4. To scroll through the mode options, press the right configuration button repeatedly until the desired mode is displayed. See Table 6-1.

TABLE 0-1. LOD Meter Modes.			
		Options	Relationship between Input Signal and Digital Display
		L in L inF Srt SrtF	Linear Linear with five-second filter Square root Square root with five-second filter
		and 20 mA=1.0, scaled per t square root is at 25% of full Filter response operates upo interval" in the following mann Display = (linear with the current signal. portional to the square root of the input current where 4 mA=0 the calibration procedure. The transition point from linear to scale flow. n "present input" and "input received in the previous five second
Store the Information			outtons simultaneously for two seconds. Note " for approximately 7.5 seconds while the d.
Set the Display	6.	Press the left button for tw	vo seconds.
Equivalent to a 4 mA Signal			numbers, press the left configuration button and , press the right configuration button. Set the Id 1000.
		To store the information, j for two seconds.	press both configuration buttons simultaneously
Set the Display	9.	Press the right button for	two seconds.
Equivalent to a 20 mA Signal		the display and to increme	numbers, press the left configuration button on ent the numbers, press the right configuration between –999 and 9999. The sum of the 4 mA not exceed 9999.
		To store the information, j for two seconds. The LCD	press both configuration buttons simultaneously meter is now configured.
Replace the Cover		Make sure the rubber gas cover, and replace the reta	ket is seated properly, replace the transparent ining ring.

LCD Meter Assembly

Figure 6-3 shows the mounting hardware required to properly install the LCD meter on a Model 444 transmitter. This mounting hardware may also be used with the Rosemount universal (analog) meter.

FIGURE 6-3. LCD Meter Exploded View



LCD Meter Specifications

Functional Specifications

Input Signal

4–20 mA dc.

Meter Indication

4-digit LCD showing -999 to 9999. A 20-segment bar graph directly represents the 4–20 mA current.

Scaling/Calibration

4 mA Point Limits: –999 to 1000.

Span limits: 0200 to 9999.

The sum of the 4 mA point and span must not exceed 9999.

Adjustments are made using non-interactive zero and span buttons.

Hazardous Locations Certifications

Approved for use with Rosemount Models 444, 751, 1135, 1144, and 1151.

6-4

Overload Limitation

666 mA.

Temperature Limits

Storage: -40 to 85 °C (-40 to 185 °F). Operating: -20 to 70 °C (-4 to 158 °F).

Between temperatures –40 to –20 °C (–40 to –4 °F), the loop is intact and the meter is not damaged.

Humidity Limitation

0 to 95% non-condensing relative humidity.

Update Period

750 ms.

Response Time

Responds to changes in input within a maximum of two update periods. If the filter is activated, then the display responds to the change within nine update periods.

nce

0.05% of calibrated range ±1 digit.

Analog Bar Graph Resolution

0.05% of calibrated range.

Digital Display Resolution

Indication Accuracy

0.25% of calibrated range ±1 digit.

Stability

Over Time: 0.1% of calibrated range ± 1 digit per six months.

Temperature Effect

0.01% of calibrated range per °C on zero. 0.02% of calibrated range per °C on span over the operating temperature range.

Power Interrupt

All calibration constants are stored in EEPROM memory and are not affected by power loss.

Failure Mode

LCD meter failure will not affect transmitter operation.

Under/Over Range Indication

Input current < 3.5 mA: Display blank. Input current > 22.0 mA: Display flashes 112.5% of full scale value or 9999, whichever is less.

Physical Specification Meter Size

2¼-inch diameter face with ½-inch high characters.

Performance Specifications

ANALOG METER

The analog meter plugs directly into the Model 444 to provide an accurate local indication of user-specified units. It requires an analog 4-20 mA dc, 10-50 mA dc, or 40-200 mV dc transmitter output from a two-wire transmitter, and adds no voltage drop in the 4-20 mA current loop when connected directly across the transmitter test terminals.

The large 2¹/₄-inch diameter meter face has a two-inch long scale for easy readability, as shown in Figure 6-4. A meter-zero adjustment is located on the meter faceplate. You can rotate the meter in 90-degree increments within the transmitter housing for convenient viewing.

FIGURE 6-4. Analog Meter Face.

	PERCENT 0 PERCENT 0 PERCENT 0
Analog Meter Specifications	
Functional	Input Signal
Specifications	4–20 mA dc 10–50 mA dc 40–200 mV } Maximum series resistance is 10 ohms for milliameters.
	Meter Indication
	0 to 100% linear scale.
	Special optional ranges.
	Overload Limit
	150% of rated end scale value for two minutes.
	Temperature Limits -40 to 65 °C (-40 to 150 °F).
	Humidity Limit
	0 to 100% relative humidity.
	Zero Adjustment
	Adjustment screw on face of meter.
Performance	Indication Accuracy

Performance Specifications

Indication Accuracy ±2% of calibrated span.

Temperature Effect

Less than 2% of full scale at any point within the temperature limits.

Physical Specification Meter Size

2¹/₄-inch diameter face with 2-inch long scale.



Hazardous Locations Certifications Drawings

Rosemount Drawing 00444-0261, 2 Sheets: Model 444 Explosion-proof Installation Drawing, Factory Mutual.

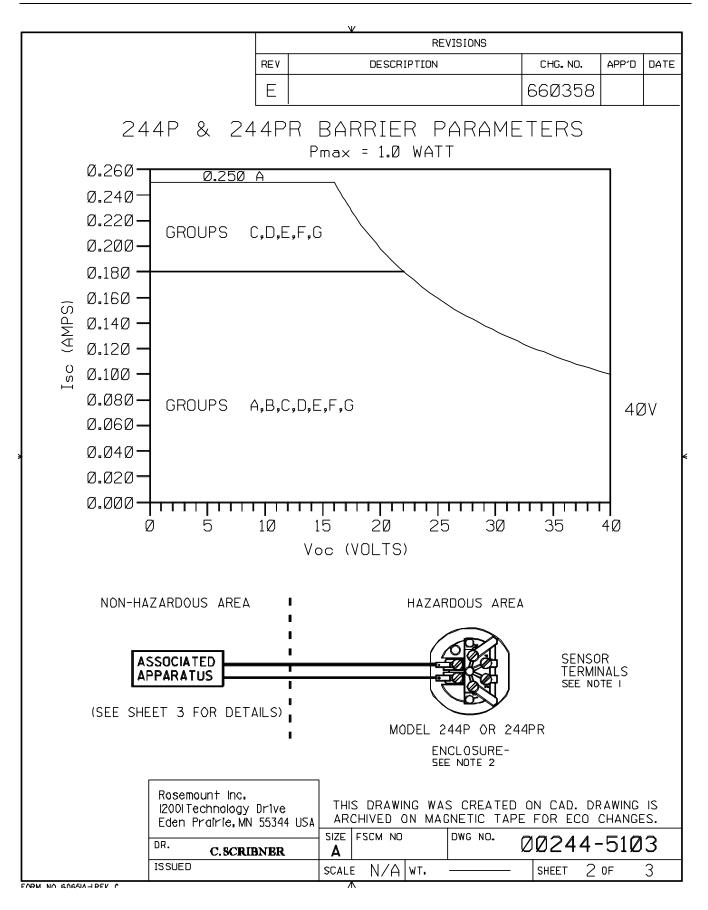
Rosemount Drawing 01151-0214, 6 Sheets: Index of Intrinsically Safe Barrier Systems and Entity parameters for 444, 1135, 1144, 1151, and 2051 Transmitters and 751 Field Indicators.

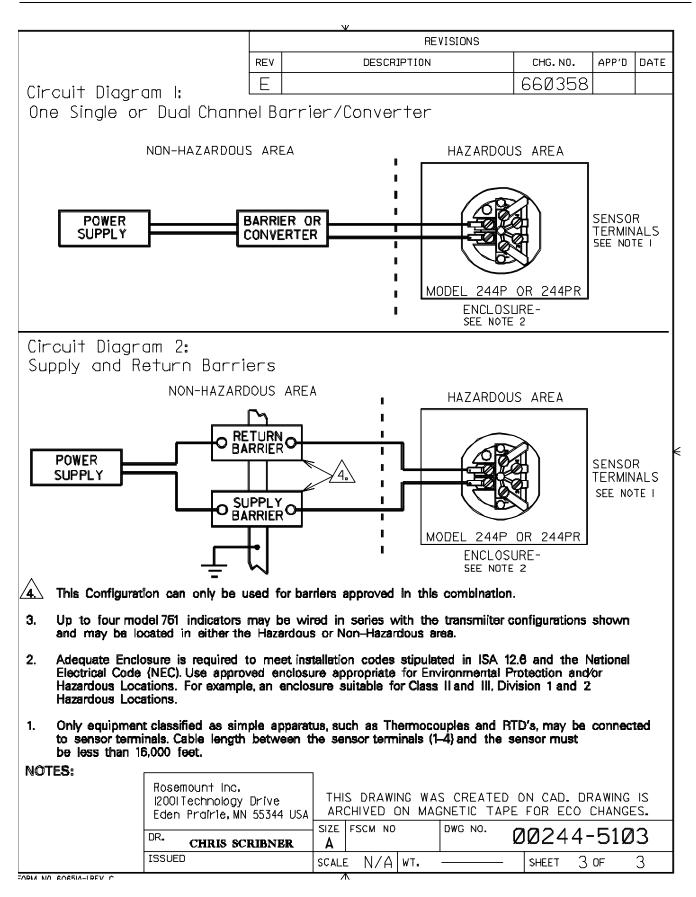
Rosemount Drawing 00444-0034, 2 Sheets: CSA Intrinsic Safety Approvals for Model 444.

Rosemount Drawing 00444-0264, 1 Sheet: Model 444 SAA Intrinisc Safety Configuration

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Appendix

B

Temperature Sensor Reference Information

TABLE B-1. Resistance Versus Temperature Curve R₀=100.00 Ω , α =0.00385 Reference Standard IEC 751.

0	_10	-20	_30	°C _40	-50	-60	-70	-80	-90
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18.49									
60.25	56.19	52.11	48.00	43.87	39.71	35.53	31.32	27.08	22.80
100	96.09	92.16	88.22	84.27	80.31	76.33	72.33	68.33	64.30
0	10	20	30	40	50	60	70	80	90
100	103.90	107.79	111.67	115.54	119.40	123.24	127.07	130.89	134.70
138.50	142.29	146.06	149.82	153.58	157.31	161.04	164.76	168.46	172.16
175.84	179.51	183.17	186.82	190.45	194.07	197.69	201.29	204.88	208.45
212.02	215.57	219.12	222.65	226.17	229.67	233.17	236.65	240.13	243.59
247.04	250.48	253.90	257.32	260.72	264.11	267.49	270.86	274.22	277.56
280.90	284.22	287.53	290.83	294.11	297.39	300.65	303.91	307.15	310.38
313.59	316.80	319.99	323.18	326.35	329.51	332.66	335.79	338.92	342.03
345.13	348.22	351.30	354.37	357.42	360.47	363.50	366.52	369.53	372.52
375.51	378.48	381.45	384.40	387.33					
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					°F					
°F	0	-10	-20	-30	-40	-50	-60	-70	-80	-90
-300	25.18	22.80	20.41	18.01						
-200	48.46	46.17	43.87	41.56	39.25	36.93	34.60	32.26	29.91	27.55
-100	71.00	68.77	66.54	64.30	62.05	59.80	57.55	55.28	53.02	50.74
0	93.03	90.85	88.66	86.47	84.27	82.07	79.87	77.66	75.44	73.22
°F	0	10	20	30	40	50	60	70	80	90
0	93.03	95.21	97.39	99.57	101.74	103.90	106.07	108.22	110.38	112.53
100	114.68	116.83	118.97	121.11	123.24	125.37	127.50	129.62	131.74	133.86
200	135.97	138.08	140.18	142.29	144.38	146.48	148.57	150.66	152.74	154.82
300	156.90	158.97	161.04	163.11	165.17	167.23	169.29	171.34	173.39	175.43
400	177.47	179.51	181.54	183.57	185.60	187.62	189.64	191.66	193.67	195.68
500	197.69	199.69	201.69	203.68	205.67	207.66	209.64	211.62	213.60	215.57
600	217.54	219.51	221.47	223.43	225.38	227.34	229.28	231.23	233.17	235.11
700	237.04	238.97	240.90	242.82	244.74	246.65	248.57	250.48	252.38	254.28
800	256.18	258.07	259.96	261.85	263.74	265.62	267.49	269.36	271.23	273.10
900	274.96	276.82	278.67	280.53	282.37	284.22	286.06	287.90	289.73	291.56
1000	293.38	295.21	297.03	298.84	300.65	302.46	304.27	306.07	307.87	309.66
1100	311.45	313.24	315.02	316.80	318.58	320.35	322.12	323.88	325.64	327.40
1200	329.16	330.91	332.66	334.40	336.14	337.88	339.61	341.34	343.07	344.79
1300	346.51	348.22	349.93	351.64	353.35	355.05	356.74	358.44	360.13	361.81
1400	363.50	365.18	366.85	368.52	370.19	371.86	373.52	375.18	376.18	378.48
1500	380.13	381.77	383.41	385.05	386.68	388.31	389.94			

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